# Synchronous Sequential Circuit

- ✓ The change of internal state occurs in response to the synchronized clock pulses.
- ✓ Data are read during the clock pulse (e.g. rising-edge triggered)
- It is supposed to wait long enough after the external input changes for all flip-flop inputs to reach a steady value before the next clock pulse
- ✓ Unsuitable Situations:
  - Inputs can change at any time and cannot be synchronized with a clock
  - Circuit is large, a cost in time of transitions can not be avoided

# Asynchronous Circuits

- $\checkmark$  Not synchronized by a common clock
- ✓ States change immediately after input changes
- ✓ For a given value of input variables, the system is stable if the circuit reaches a steady state condition.
- $\checkmark$  The circuit reaches a steady-state condition when y<sub>i</sub> = Y<sub>i</sub> for all i.
- A transition from one stable state to another occurs only in response to a change in an input variable
- Fundamental-mode operation
  - The input signals change only when the circuit is in a stable condition
  - The input signals change one at a time
- ✓ The time between two input changes must be longer than the time it takes the circuit to reach a stable state.
- Timing is a Major Problem because of unequal delays through various paths in the circuit

# Why Asynchronous Sequential Circuits?

#### Asynchronous sequential circuits basics

- ✓ No clock signal is required
- Internal states can change at any instant of time when there is a change in the input variables
- ✓ Have better performance but hard to design due to timing problems

#### Why Asynchronous Circuits?

- Accelerate the speed of the machine (no need to wait for the next clock pulse).
- ✓ Simplify the circuit in the small independent gates.
- Necessary when having multi circuits each having its own clock.

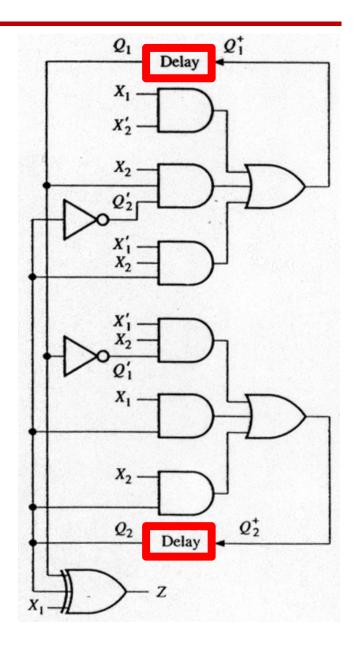
#### Analysis Procedure

 The analysis consists of obtaining a table or a diagram that describes the sequence of internal states and outputs as a function of changes in the input variables.

## Example Circuit

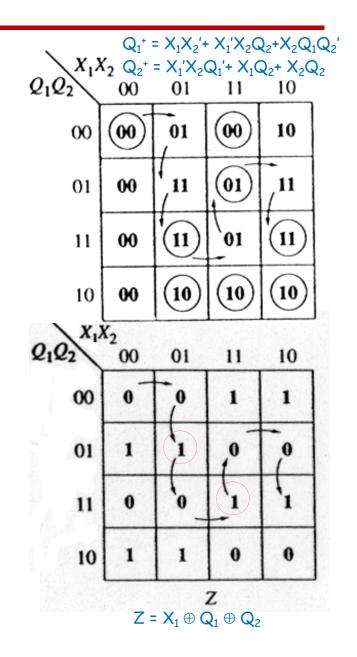
- ✓ First construction of Asynchronous Circuits:
  - using only gates
  - with feedback paths
- ✓ Analysis:
  - Lump all of the delay associated with each feedback path into a "delay" box
  - Associate a state variable with each delay output
  - Construct the flow table
- ✓ Network equations

$$Q_{1}^{+} = X_{1}X_{2}' + X_{1}'X_{2}Q_{2} + X_{2}Q_{1}Q_{2}'$$
$$Q_{2}^{+} = X_{1}'X_{2}Q_{1}' + X_{1}Q_{2} + X_{2}Q_{2}$$
$$Z = X_{1} \oplus Q_{1} \oplus Q_{2}$$



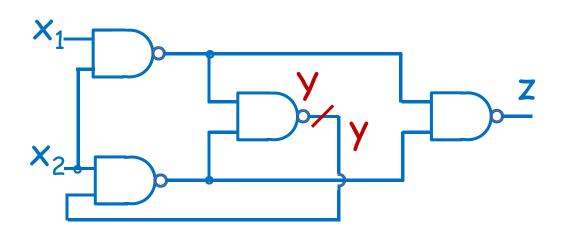
### Example Circuit: Output Table

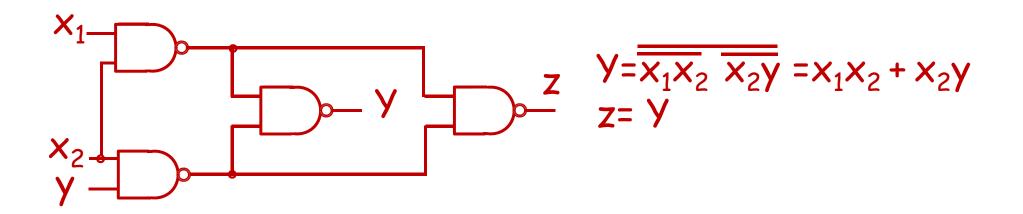
- ✓ 1. Starting in total state  $X_1X_2Q_1Q_2=0000$
- $\checkmark$  2. Input changes to 01
  - Internal state changes to 01 and then to 11.
- ✓ 3. Input changes to 11.
  - Go to unstable total state 1111 and then to 1101.
- $\checkmark$  4. Input changes to 10.
  - Go to unstable total state 1001 and then to 1011.
- ✓ The output sequence: 0(0)(1)0(1)0(0)1
  - Condensed to the form
     O (1) O (1) O 1.
  - Two transient 1 outputs is dangerous can be eliminated by proper design.



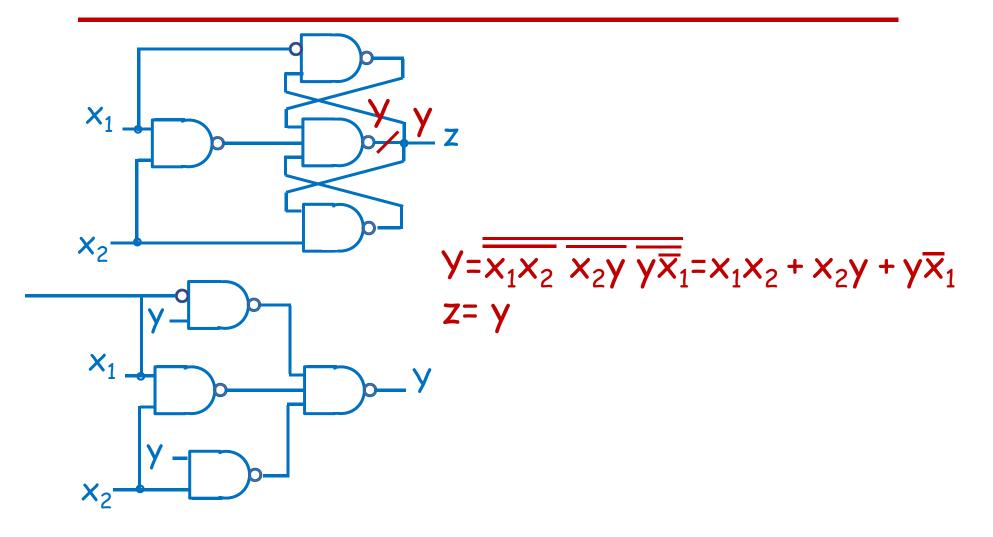
- Transition table is useful to analyze an asynchronous circuit from the circuit diagram. Procedure to obtain transition table:
  - 1. Determine all feedback loops in the circuits
  - 2. Mark the input  $(y_i)$  and output  $(Y_i)$  of each feedback loop
  - 3. Derive the Boolean functions of all Y's
  - 4. Plot each Y function in a map and combine all maps into one table (flow table)
  - 5. Circle those values of Y in each square that are equal to the value of y in the same row (stable states)

#### Asynchronous Sequential Analysis

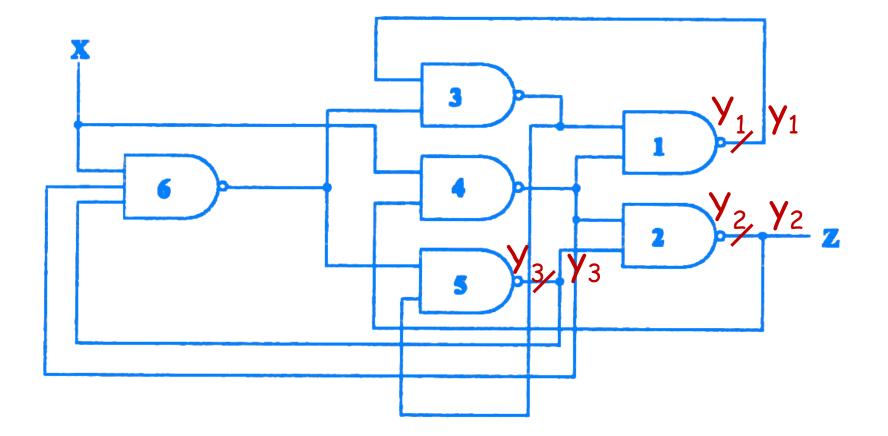




Asynchronous Sequential Analysis



# Asynchronous Sequential Analysis

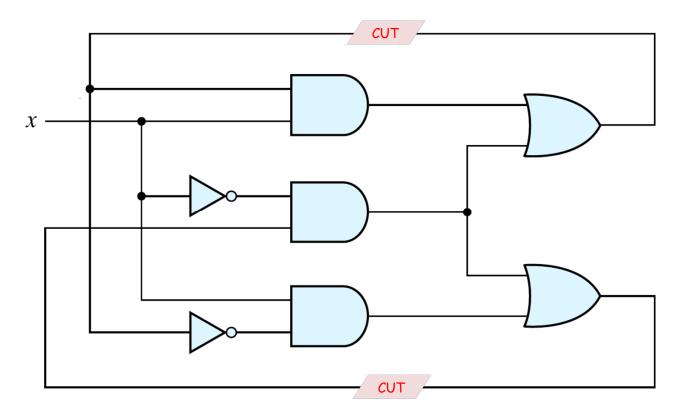


Asynchronous Sequential Circuit

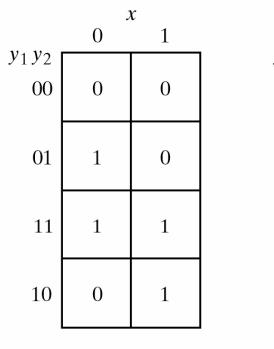
 $\checkmark$  The state variables:  $Y_1$  and  $Y_2$ 

• 
$$\mathbf{Y}_1 = \mathbf{x}\mathbf{y}_1 + \overline{\mathbf{x}}\mathbf{y}_2$$

•  $Y_2 = x\overline{y}_1 + \overline{x}y_2$ 

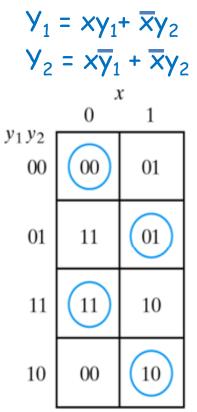


- Combine the internal state with input variables
  - Stable total states:
     y<sub>1</sub>y<sub>2</sub>x = 000, 011, 110 and 101

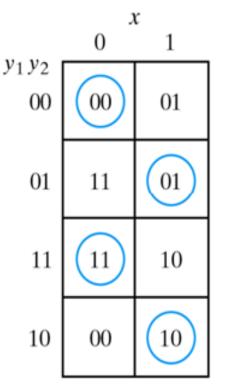


(a) Map for  $Y_1 = xy_1 + x'y_2$ 

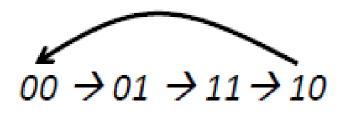
> (b) Map for  $Y_2 = xy'_1 + x'y_2$

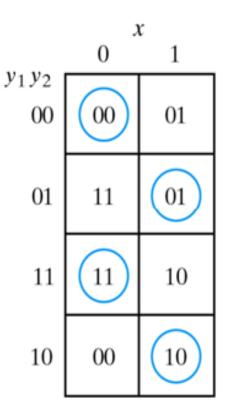


- ✓ In an asynchronous sequential circuit, the internal state can change immediately after a change in the input.
- It is sometimes convenient to combine the internal state with input value together and call it the Total State of the circuit. (Total state = Internal state + Inputs)
- $\checkmark\,$  In the example , the circuit has
  - 4 stable total states: (y<sub>1</sub>y<sub>2</sub>x= 000, 011, 110, and 101)
  - 4 unstable total states: (y<sub>1</sub>y<sub>2</sub>x= 001, 010, 111, and 100)



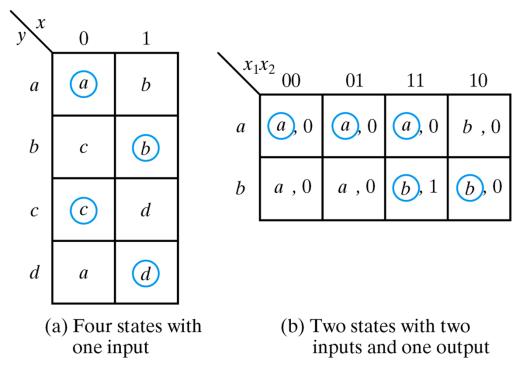
- ✓ If y=00 and x=0⇒Y=00 (Stable state)
- ✓ If x changes from 0 to 1 while y=00, the circuit changes Y to 01 which is temporary unstable condition (Y≠y)
- ✓ As soon as the signal propagates to make Y=01, the feedback path causes a change in y to 01. (transition form the first row to the second row)
- ✓ If the input alternates between 0 and 1, the circuit will repeat the sequence of states:





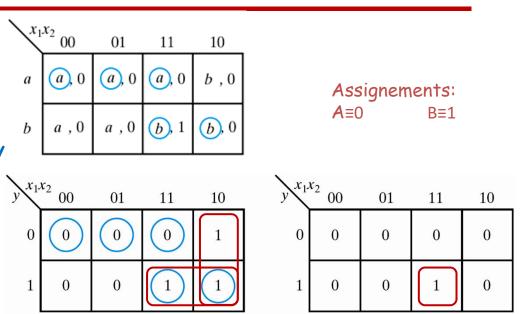
#### Flow Table

- A flow table is similar to a transition table except that the internal state are symbolized with letters rather than binary numbers.
- ✓ It also includes the output values of the circuit for each stable state.

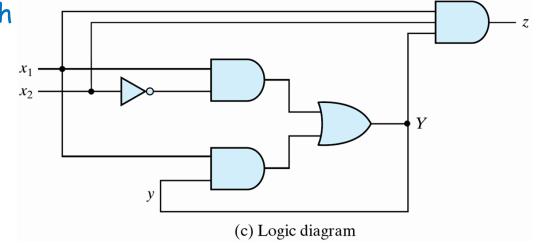


#### Flow Table

✓ In order to obtain the circuit described by a flow table, it is necessary to convert the flow table into a transition table from which we can derive the logic diagram.  $x_1x_2$ 00 0 1 0

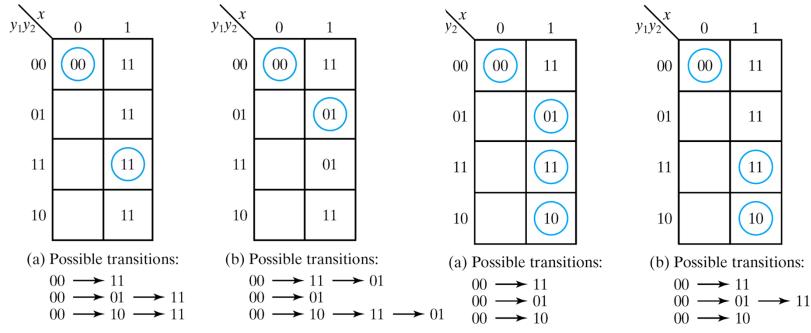


 This can be done through the assignment of a distinct binary value to each state.



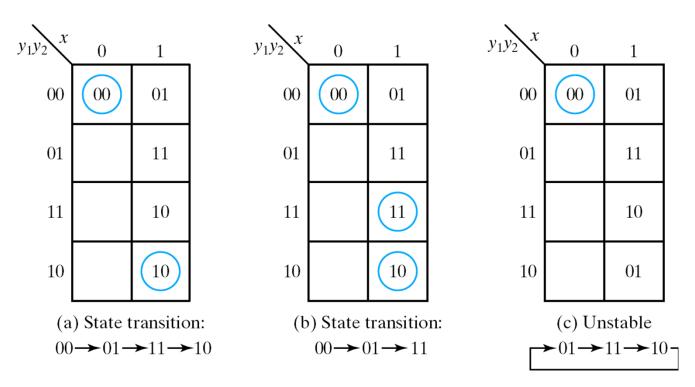
# Race condition

- Two or more binary state variables will change value when one input variable changes.
- ✓ Cannot predict state sequence if unequal delay is encountered.
- Non-critical race: The final stable state does not depend on the change order of state variables
- Critical race: The change order of state variables will result in different stable states. Must be avoided !!



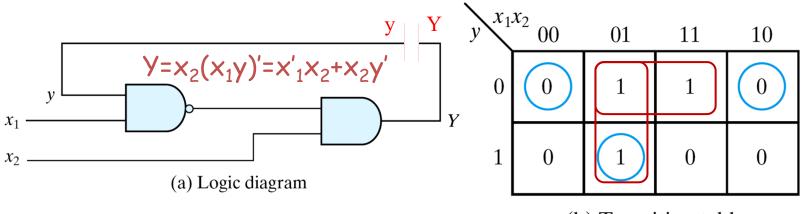
#### **Race Solution**

- ✓ It can be solved by making a proper binary assignment to the state variables.
- ✓ The state variables must be assigned binary numbers in such a way that only one state variable can change at any one time when a state transition occurs in the flow table.



#### Stability Check

- Asynchronous sequential circuits may oscillate between unstable states due to the feedback
  - Must check for stability to ensure proper operations
- $\checkmark$  Can be easily checked from the transition table
  - Any column has no stable states  $\longrightarrow$  unstable Ex: when  $x_1x_2=11$  in (b), Y and y are never the same

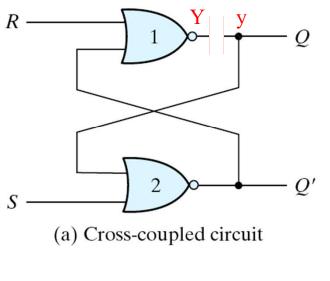


(b) Transition table

### Latches in Asynchronous Circuits

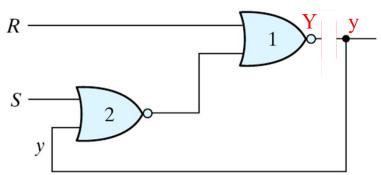
- ✓ The traditional configuration of asynchronous circuits is using one or more feedback loops
  - No real delay elements.
- ✓ It is more convenient to employ the SR latch as a memory element in asynchronous circuits
  - Produce an orderly pattern in the logic diagram with the memory elements clearly visible.
- ✓ SR latch is an asynchronous circuit
  - So will be analyzed first using the method for asynchronous circuits.

#### SR Latch with NOR Gates

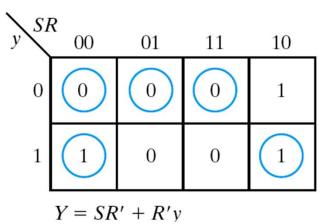


S I	R Q	Q'	
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	) 1 ) 1 l 0 ) 0 l 0	$egin{array}{c} 0 \\ 0 \\ 1 \\ 1 \\ 0 \end{array}$	(After $SR = 10$ ) (After $SR = 01$ )

(b) Truth table



(c) Circuit showing feedback



(d) Transition table

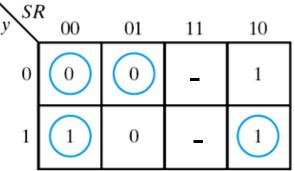
The condition to be avoided is that both S and R inputs must not be 1 simultaneously. This condition is avoided when SR = 0 (i.e., ANDing of S and R must always result in 0).

When SR = 0 holds at all times, the excitation function derived previously:

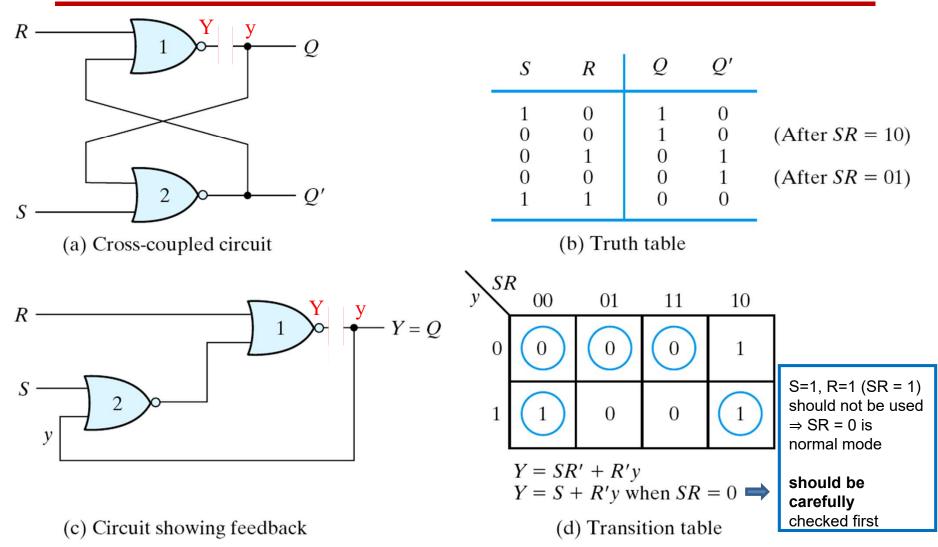
$$Y = SR' + R'y$$

can be expressed as:

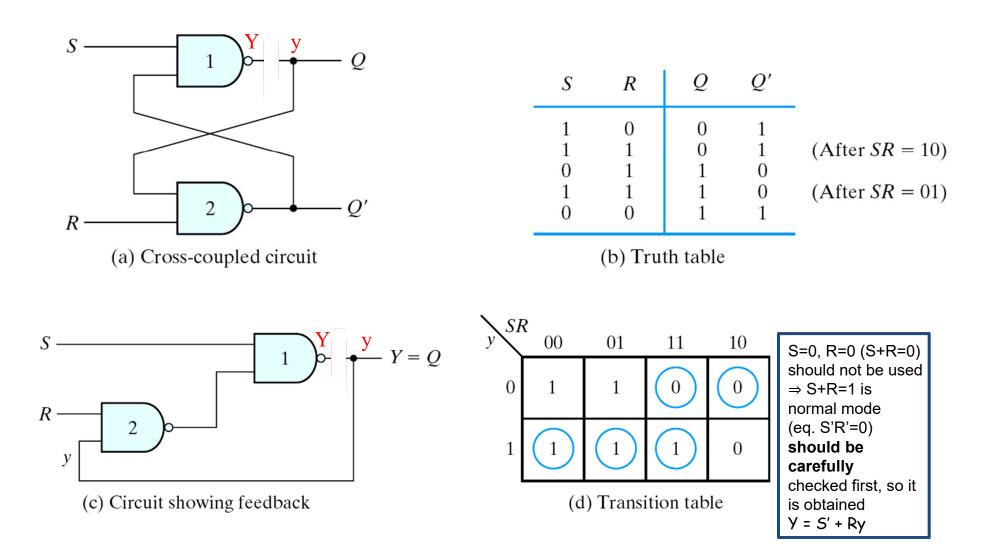
$$Y = S + R'y$$

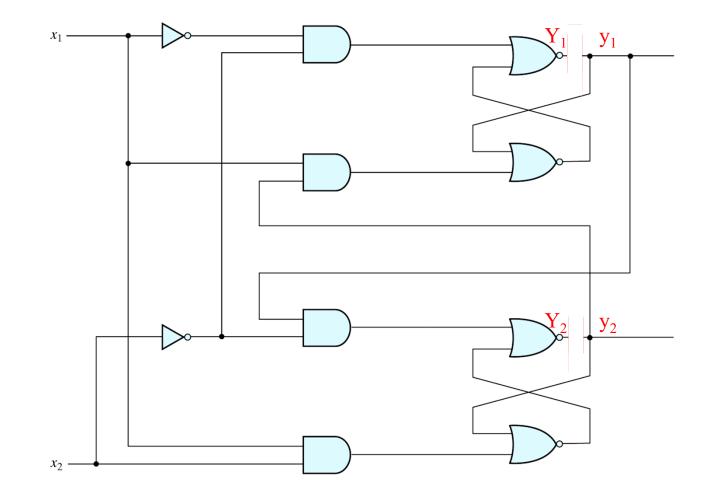


#### SR Latch with NOR Gates

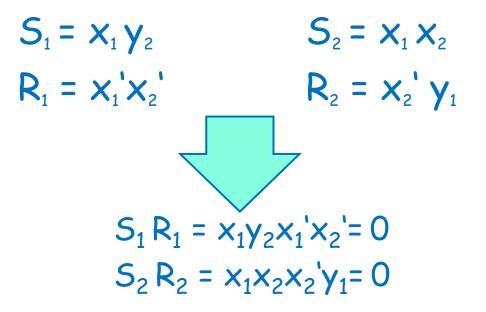


#### SR Latch with NAND Gates





- The procedure for analyzing an asynchronous sequential circuit with SR latches can be summarized as follows:
  - Label each latch output with  $Y_i$  and its external feedback path with  $y_i$  for i=1,2,...,k
  - \* Derive the Boolean functions for the  $S_{\rm i}$  and  $R_{\rm i}$  inputs in each latch.



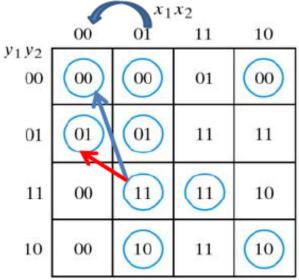
 Check whether SR =0 for each NOR latch or whether S'R' = 0 for each NAND latch. (if either of these two conditions is not satisfied, there is a possibility that the circuit may not operate properly)

> $S_1 R_1 = x_1 y_2 x_1' x_2' = 0$  $S_2 R_2 = x_1 x_2 x_2' y_1 = 0$

 Evaluate Y = S + R'y for each NOR latch or Y = S' + Ry for each NAND latch.

$$Y_{1} = S_{1} + R_{1}' y_{1} = x_{1}y_{2} + x_{1}y_{1} + x_{2}y_{1}$$
$$Y_{2} = S_{2} + R_{2}' y_{2} = x_{1}x_{2} + x_{2}y_{2} + y_{1}'y_{2}$$

- Construct a map, with the y's representing the rows and the x inputs representing the columns.
- Plot the value of  $Y=Y_1Y_2...Y_k$  in the map.
- Circle all stable states such that Y=y. The result is then the transition table.
- The transition table shows that the circuit is **stable**
- Race Conditions: there is a **critical race** condition when the circuit is initially in total state  $y_1y_2x_1x_2 = 1101$  and  $x_2$  changes from 1 to 0.
- The circuit should go to the total state <u>0000</u>.
- If  $Y_1$  changes to 0 before  $Y_2$ , the circuit goes to total state 0100 instead of 0000.



**Transition Table** 

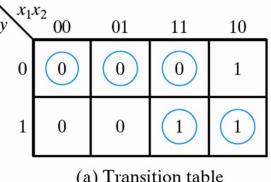
 $Y_{1} = x_{1}y_{2} + x_{1}y_{1} + x_{2}y_{1}$  $Y_{2} = x_{1}x_{2} + x_{2}y_{2} + y_{1}'y_{2}$ 

#### **Implementation Procedure**

- Procedure to implement an asynchronous sequential circuits with SR latches:
  - Given a transition table that specifies the excitation function  $Y = f(y_1, -, y_n, x_1, -, x_m)$  derive a pair of maps for each  $S_i$  and  $R_i$  using the latch excitation table
  - Derive the Boolean functions for each S<sub>i</sub> and R<sub>i</sub> (do not to make S<sub>i</sub> and R<sub>i</sub> equal to 1 in the same minterm square; for NAND latch, use the complemented values)
  - Draw the logic diagram using k latches together with the gates required to generate the S and R

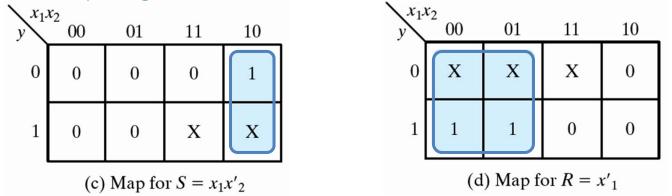
### Implementation Example

- ✓ Given a transition table  $Y = f(y_1, -, y_n, x_1, -, x_m)$ , then the general procedure for implementing a circuit with SR latches is specified by the excitation function, and can be summarized as follows:
  - Given a transition table



$$Y = x_1 x'_2 + x_1 y$$

• Determine the Boolean functions for the S and R inputs of each latch (this is done by using the latch excitation table)



### Implementation Example

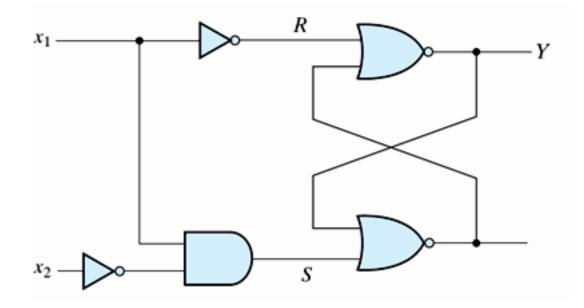
• From maps: the simplified Boolean functions are

$$S = x_1 x_2'$$
 and  $R = x_1'$  > NOR latch

 Check whether SR=0 for each NOR latch or whether S'R'=0 for each NAND latch:

 $SR = x_1x_2'x_1' = 0$ 

• Draw the logic diagram, using k latches together with the gates required to generate the S and R Boolean functions obtained in step1 (for NAND latches, use the complemented values)



### Primitive Flow Table

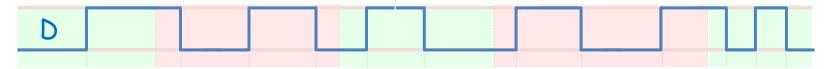
- Primitive flow table has exactly one stable total state (internal state + input) per row
- ✓ To avoid the timing problems:
  - Only one input variable changes at a time
  - Networks reach a stable total state between input changes (Fundamental Mode)
- ✓ Every change in input changes the state

# Design procedure

- 1. Obtain a primitive table from specifications
- 2. Reduce flow table by merging rows in the primitive flow table
- 3. Assign binary state variables to each row of reduced table
- 4. Assign output values to dashes associated with unstable states to obtain the output map
- 5. Simplify Boolean functions for excitation and output variables;
- 6. Draw the logic diagram

- ✓ Problem Statement:
  - Design a gated latch circuit (memory element) with two inputs, G(gate) and D(Data) and one output Q.
  - The Q output will follow the D input as long as G=1. When G goes to O, the information that was present at the D input at the time of transition is retained at the Q output.
    - Q = D when G =1
    - Q retains its value when G goes to 0

1-	1-Primitive Flow Table			Inp	outs	Output		
$\checkmark$			le is a flow table	State	D	G	Q	Comments
			total state (intern	al <sub>a</sub>	0	1	0	D = Q because $G = 1$
	state + I	nput) in eac	n row.	b	1	1	1	D = Q because $G = 1$
✓ In order t	to form the primitive flow	С	0	0	0	After state <i>a</i> or <i>d</i>		
	table, we first form a table with all	d	1	0	0	After state <i>c</i>		
				е	1	0	1	After state $b$ or $f$
	possible total states, combinations of			f	0	0	1	After state <i>e</i>
		ts and inter eous transit	ions of two inputvo	iriables (	are no	t allow	ed	
	G							



c,0 00

10

00

a,0

01

b,1 11

11

10

e,1 10

01

11

01/

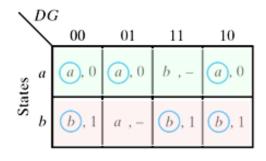
- 1-Primitive Flow Table
- One square in each row is a stable state for that row.
- $\checkmark$  First, we note that both inputs are not allowed to change at the same time.
  - We enter dash marks in each row that differs in two or more variables from the input variables associated with the stable state.
- ✓ Next it is necessary to find values for the two squares adjacent to the stable state in each row.
  - the previous table may support in deriving the necessary information.
- ✓ All outputs associated with unstable states are don't care conditions
  - We marked them with a dash.

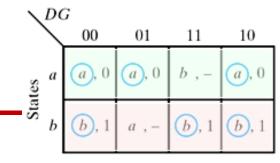
		Input	s Out	put		
	State		G (	2 Com	Comments	
	a b c d e f	0 1 0 1 1 0	1 0 1 1 0 0 0 0 0 1 0 1 0 1	D = After After After	$Q \text{ because } G = Q \text{ because } G =$ $Q \text{ because } G =$ $state \ a \text{ or } d$ $state \ c$ $state \ b \text{ or } f$ $state \ e$	
,			D	G		
		00	01	11	10	
10 00	а	с,-	<b>a</b> ,0	b ,-	- ,-	
d,0	b	- ,-	a ,-	<b>b</b> ,1	е,-	
10	с	0,0	a ,-	- ,-	d ,-	
01 f,1 00	d	С,—	-,-	b ,-	<b>(d</b> ),0	
00 10	е	f,-	- ,-	b ,-	<u>e</u> ,1	
	f	<b>(f)</b> , 1	a ,-	- ,-	е,-	
						1

- 2-Reduction of the Primitive Flow Table
- Two or more rows can be merged into one row if there are non-conflicting states and outputs in every columns.

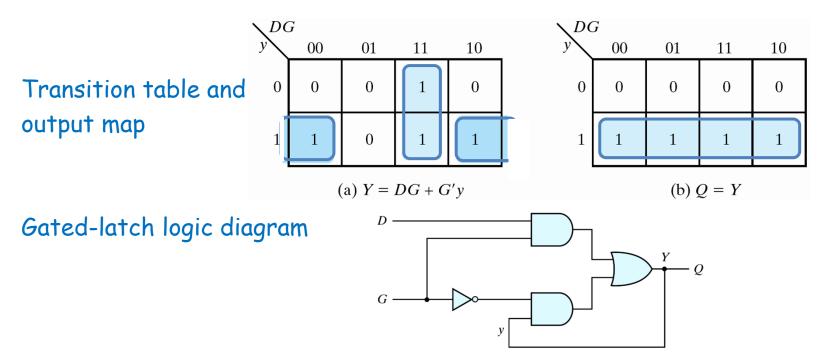
Candidates states for merging: DGDG00 01 10 00 0111 10 11 (b), 1 a), 0 b ,b a , а e , - $C_{i}$ , -- , -- . -States c),0 d ,b ,-(e), 1 a ,f, -- , -- , с b ,-(d), 0d C . -- , f a , -- , e , -

- After merged into one row:
  - Don't care entries are overwritten
  - Stable states and output values are included
  - A common symbol is given to the merged row

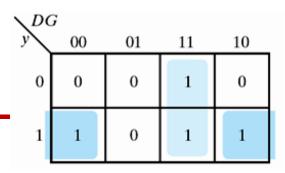




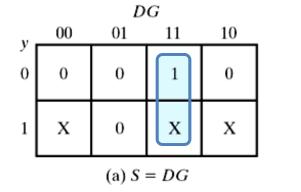
- 3-Transition Table and Logic Diagram
- ✓ In order to obtain the circuit described by the reduced flow table, it is necessary to assign a distinct binary value to each state.
- $\checkmark$  This converts the flow table to a transition table.
- ✓ A binary state assignment must be made to ensure that the circuit will be free of critical race.

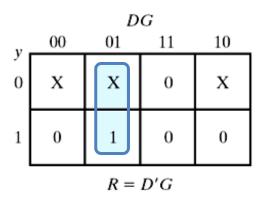


#### a=0, b=1 in this example

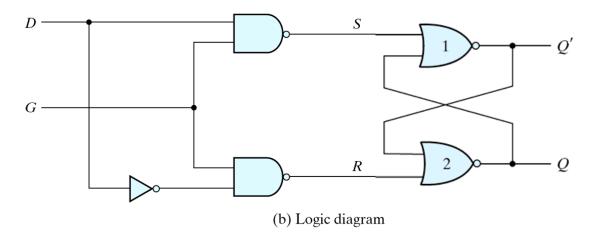








Circuit with SR latch



#### 5- Assigning Outputs to Unstable States

- ✓ While the stable states in a flow table have specific output values associated with them, the unstable states have unspecified output entries designated by a dash.
- These unspecified output values must be chosen so that no momentary false outputs occur when the circuit switches between stable states.
  - If the two stable states have the save output value, then an unstable states that are a transient state between them must have the same output.
  - If an output variable is to change as a result of a state change, then this variable is assigned a don't care condition\*.

#### 5- Assigning Outputs to Unstable States

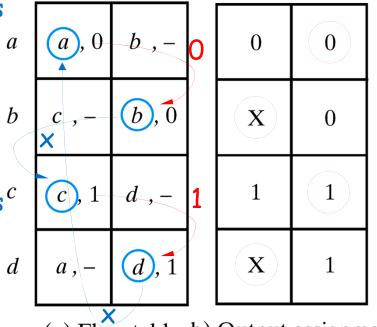
Example:

If a changes to b, the two stable states have the same output value =0 (0=>0: 0) a the transient unstable state b in the first row must have the same output value = 0

if c changes to d same for  $1 \Rightarrow 1$ : 1

If b changes to c, the two stable states<sup>c</sup> have different output values 0⇒1: x
 the transient unstable state c in the d second row is assigned a don't care condition

if d changes to a same for  $1 \Rightarrow 0: x$ 



(a) Flow table b) Output assignment