



1st Workshop on Eye Tracking Techniques, Applications and Challenges

<https://vision.unipv.it/ettac2020/>

10 January 2021

In conjunction with



Eye Movement Classification with Temporal Convolutional Networks

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Candy Gonzales
Carlos H. Morimoto

University of São Paulo - Brazil



IME-USP

supported by





What is this work about?

What is this work about?

- improving the state of the art of the EMCP

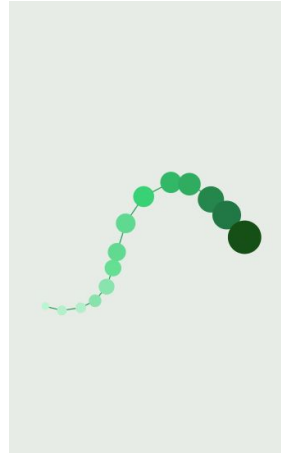
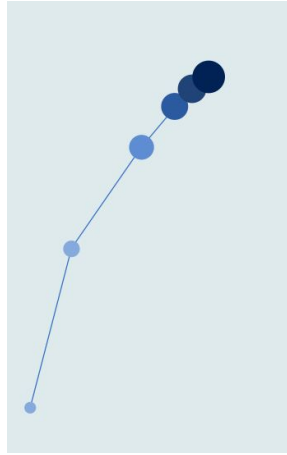
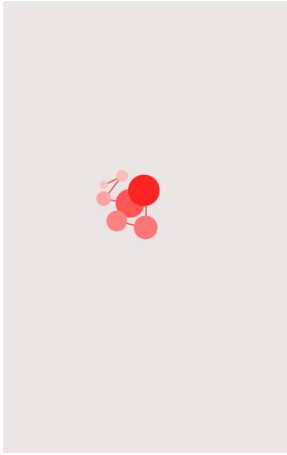
What is this work about?

- improving the state of the art of the EMCP
- improving our understanding of the problem



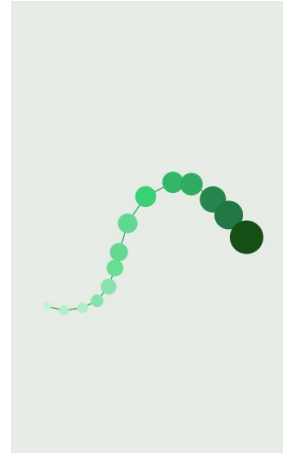
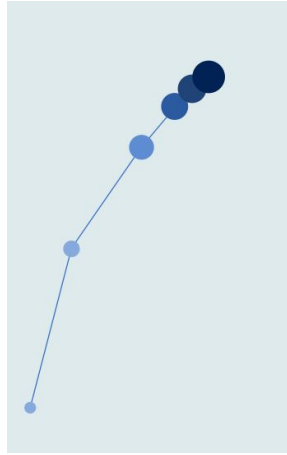
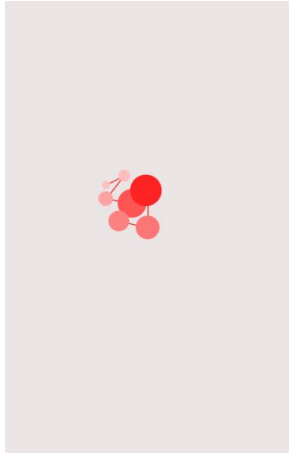
Problem statement: 3EMCP

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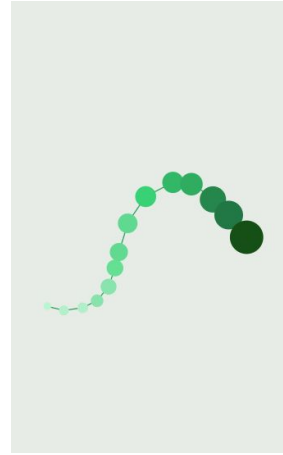
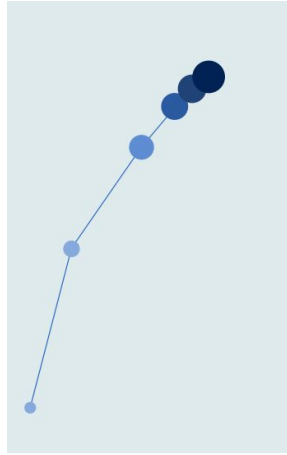
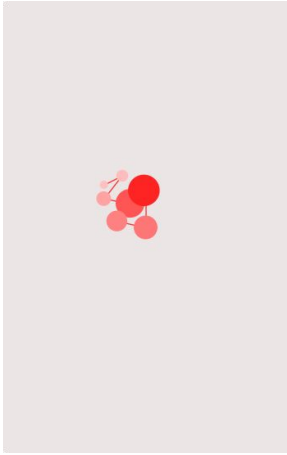
Fixations

Problem statement: 3EMCP



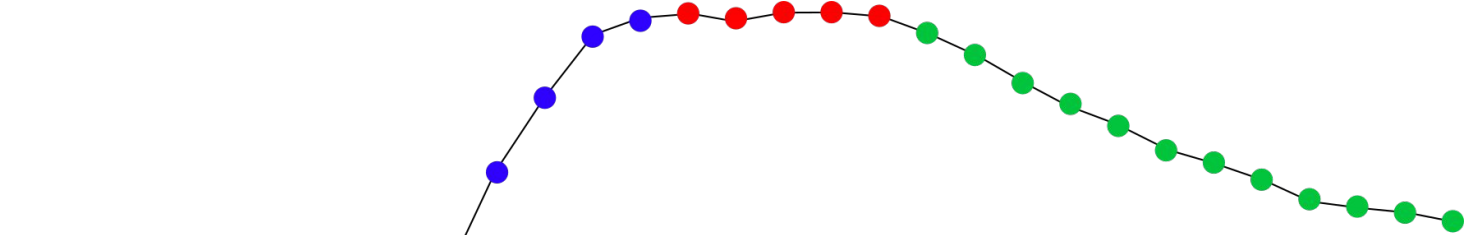
Saccades

Problem statement: 3EMCP

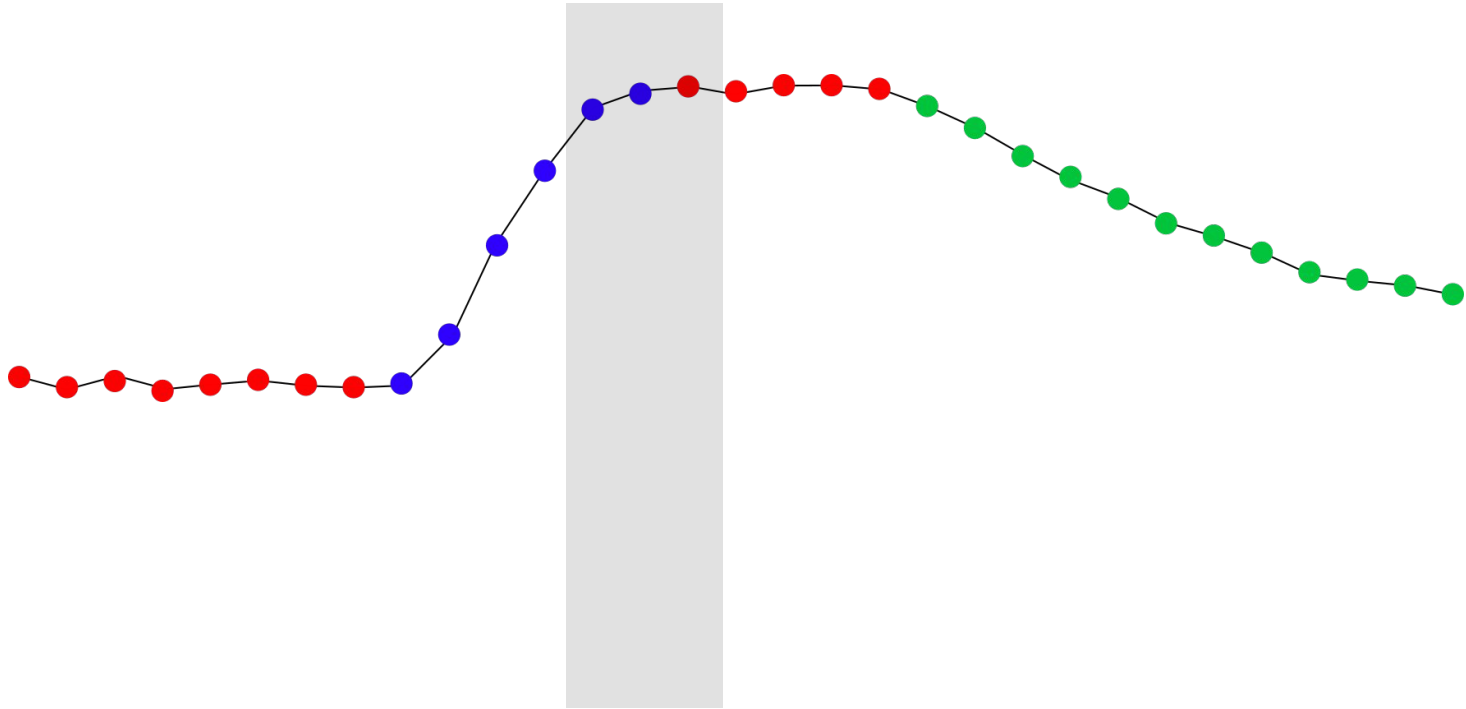


Smooth
Pursuits

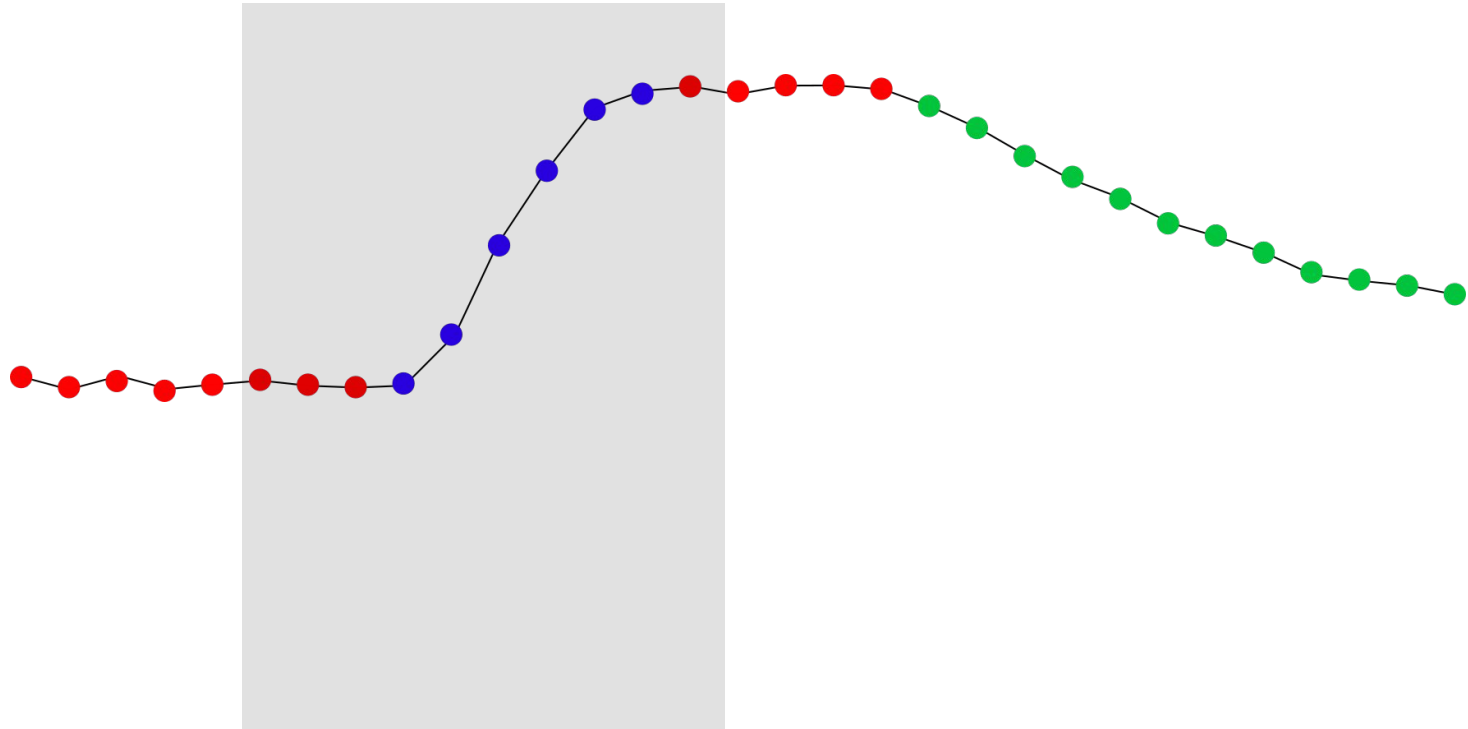
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Past works

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- threshold-based classification

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- probabilistic methods

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- threshold-based classification
- probabilistic methods
- deep learning models

End-to-end architectures

Pros

Cons

End-to-end architectures

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- high accuracy

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- no parameter setting

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- computational cost
- large datasets

End-to-end architectures

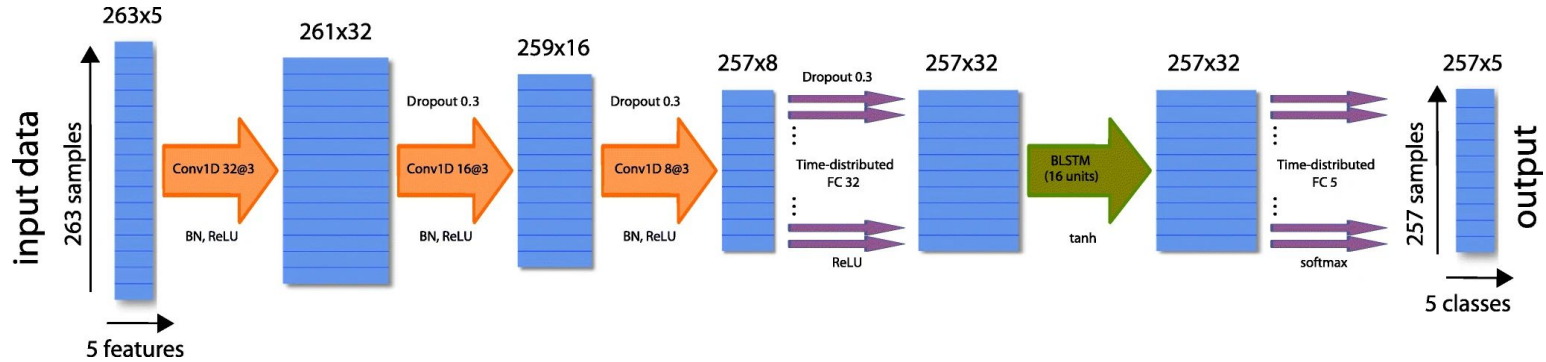
Pros

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Cons

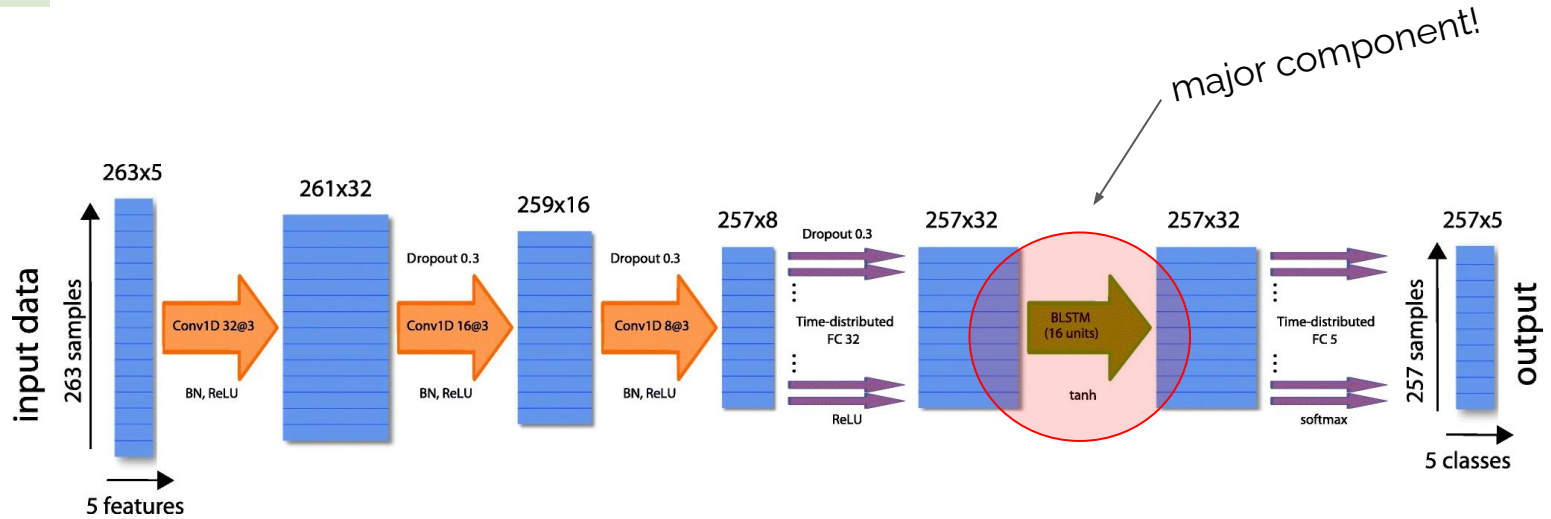
- computational cost
- large datasets
- re-training

The 1D CNN-BLSTM model



SOURCE: <https://link.springer.com/article/10.3758/s13428-018-1144-2/figures/1>

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Why TCNs?

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- memory footprint

Why TCNs?

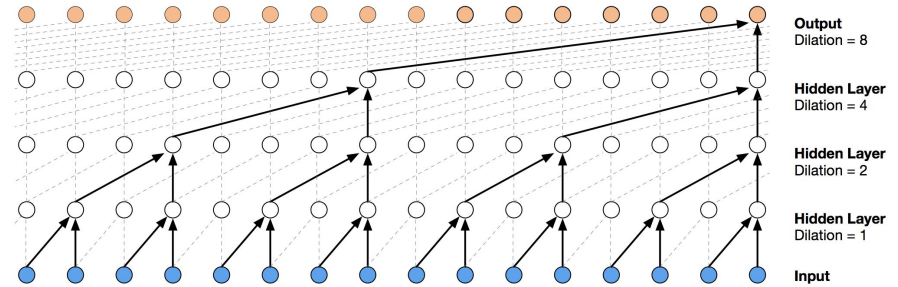
- performance \geq LSTMs, GRUs...
- highly parallel
- memory footprint
- long-term dependencies



Canonical TCNs

Canonical TCNs

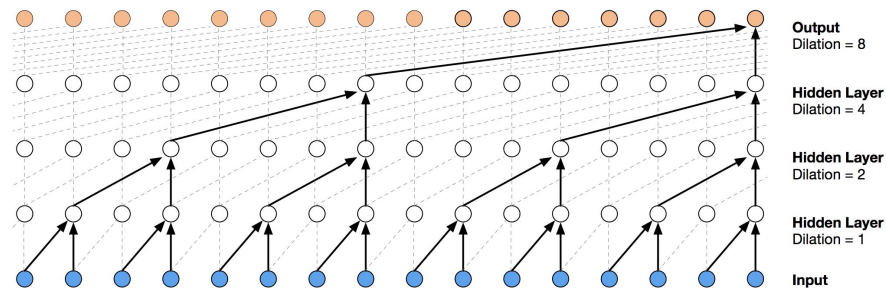
- causal convolutions



SOURCE: <https://github.com/philipperemy/keras-tcn>

Canonical TCNs

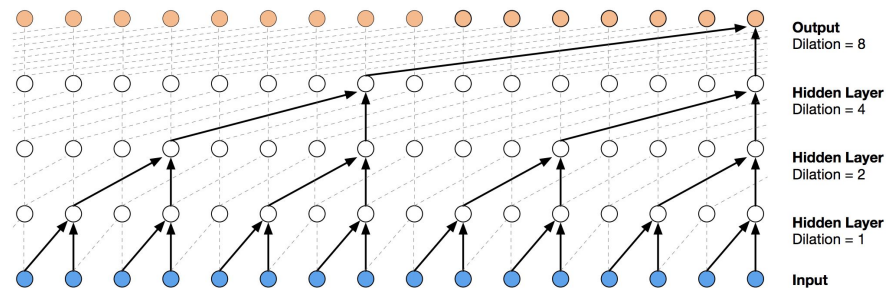
- causal convolutions
- dilations



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Canonical TCNs

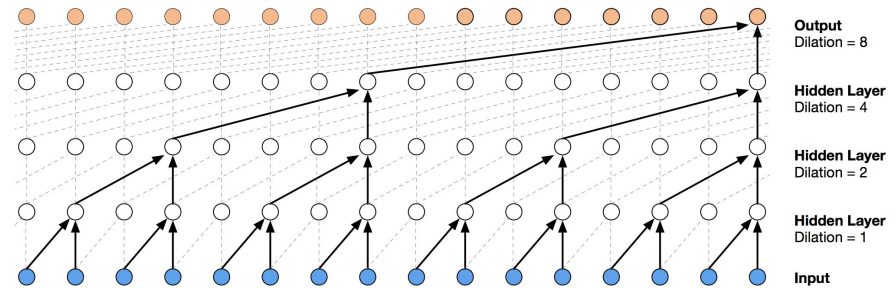
- causal convolutions
- dilations
- residual block



SOURCE: <https://github.com/philipperemy/keras-tcn>

Canonical TCNs

- causal convolutions
- dilations
- residual block
- variable input length



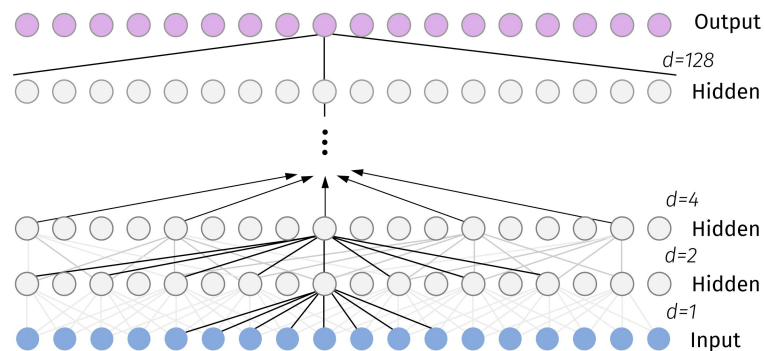
SOURCE: <https://github.com/philipperemy/keras-tcn>



Our TCN

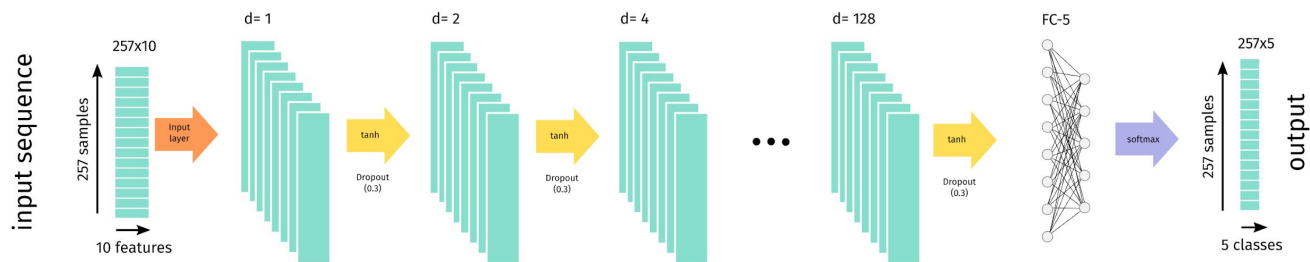
Our TCN

- non-causal convolutions



Our TCN

- non-causal convolutions
- *tanh* activation



Our TCN

- non-causal convolutions
- *tanh* activation
- specifics:

—————→ <https://github.com/elmadjian/3EMCP-with-TCNs>



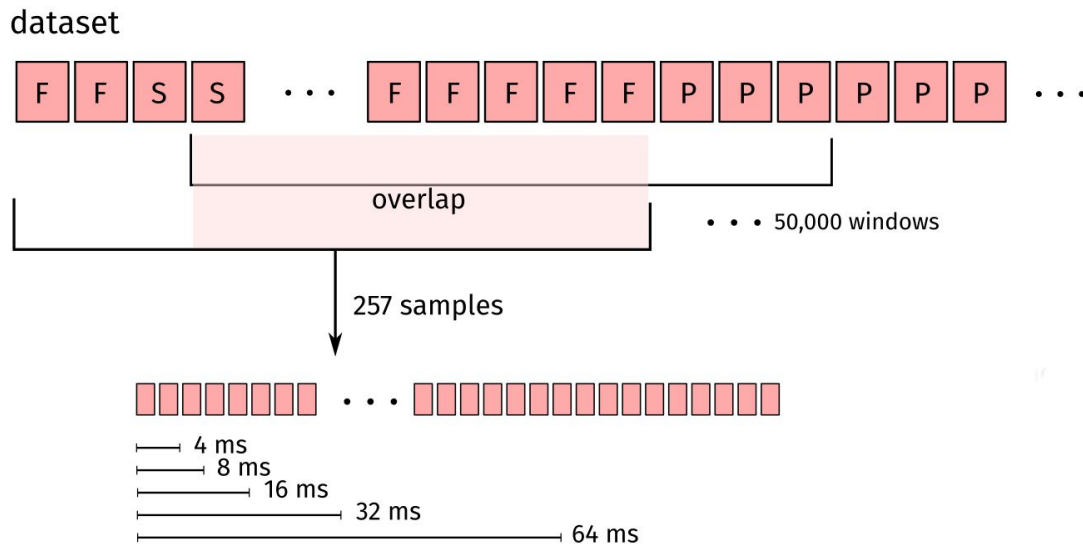
Exploratory study

Exploratory study

- feature space → *speed, direction, displacement, stddev*

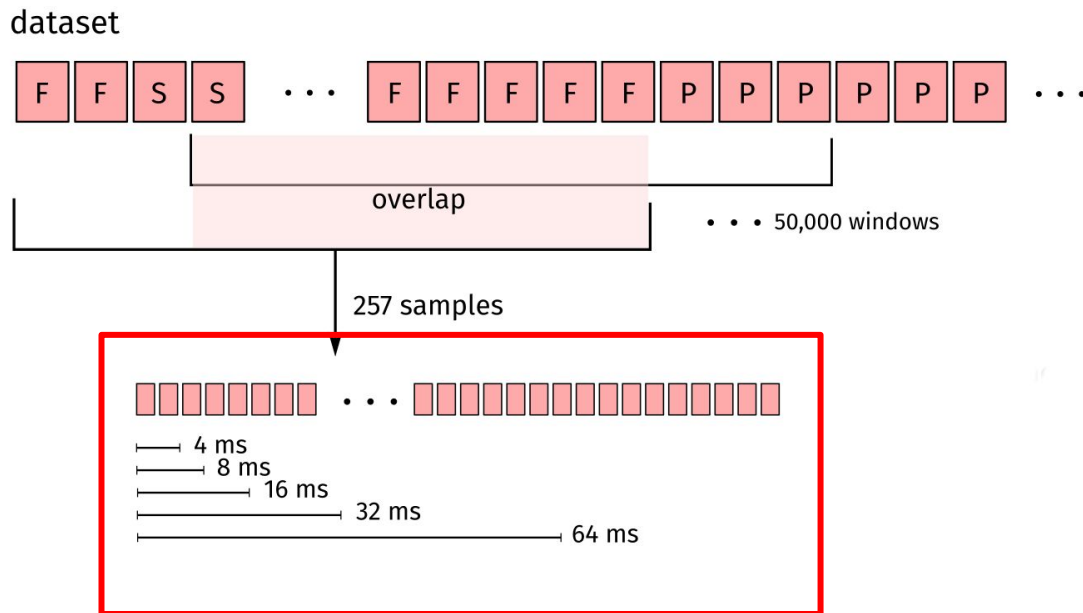
Exploratory study

- feature space
- feature scale



Exploratory study

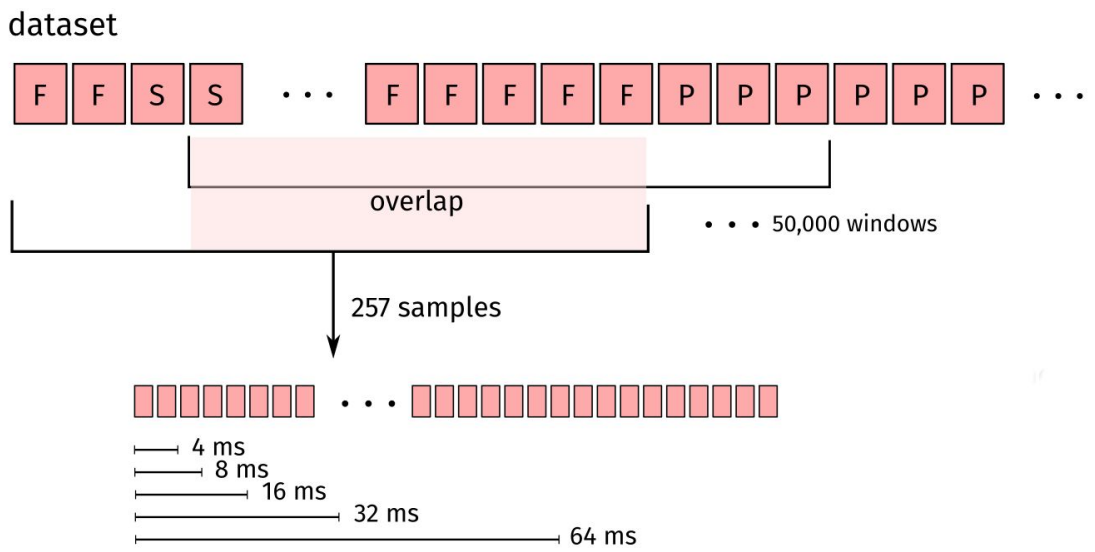
- feature space
- feature scale



+128 ms, 256 ms, 512 ms

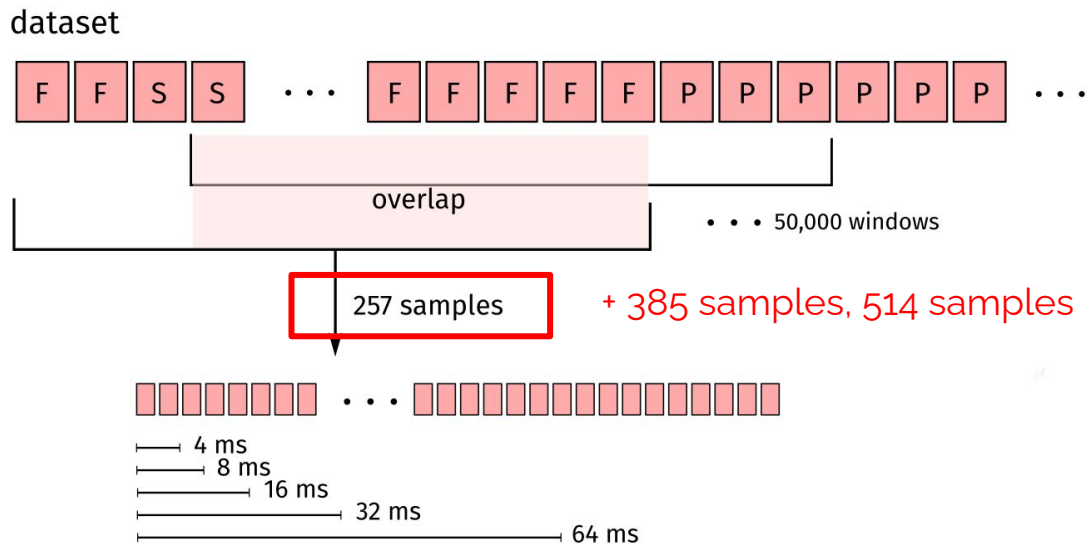
Exploratory study

- feature space
- feature scale
- window size



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- feature space
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GazeCom dataset



18 clips



47 users



21 s

GazeCom dataset



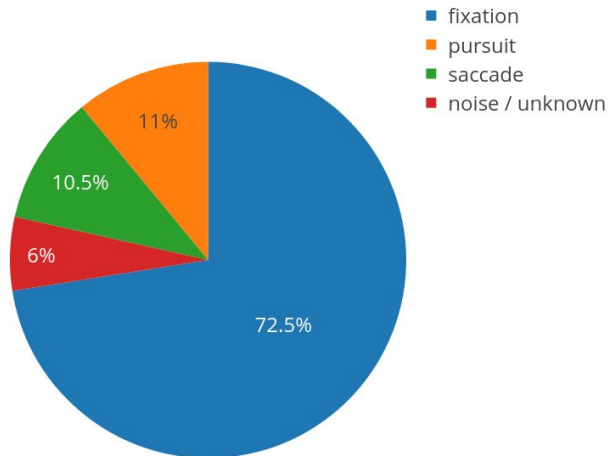
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samples

GazeCom dataset



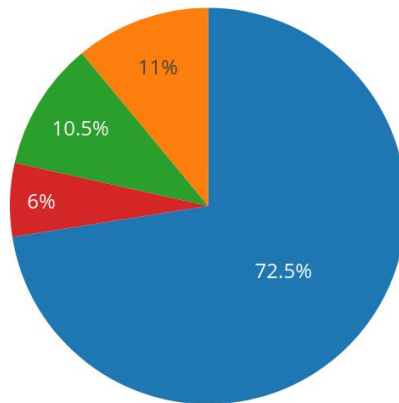
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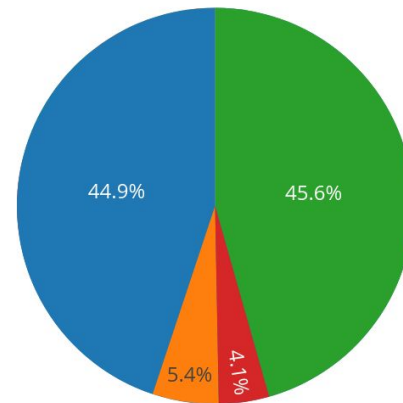


21 s



samples

- fixation
- pursuit
- saccade
- noise / unknown



events

Training

[1] Startsev, Mikhail, Ioannis Agtzidis, and Michael Dorr. "1D CNN with BLSTM for automated classification of fixations, saccades, and smooth pursuits." *Behavior Research Methods* 51.2 (2019): 556-572.

Training

LOVO, as described by Startsev et al. [1], **except** for:

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- tensorflow 2



Metrics and evaluation

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- sp_tool

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- F1-score (samples and events)

Metrics and evaluation

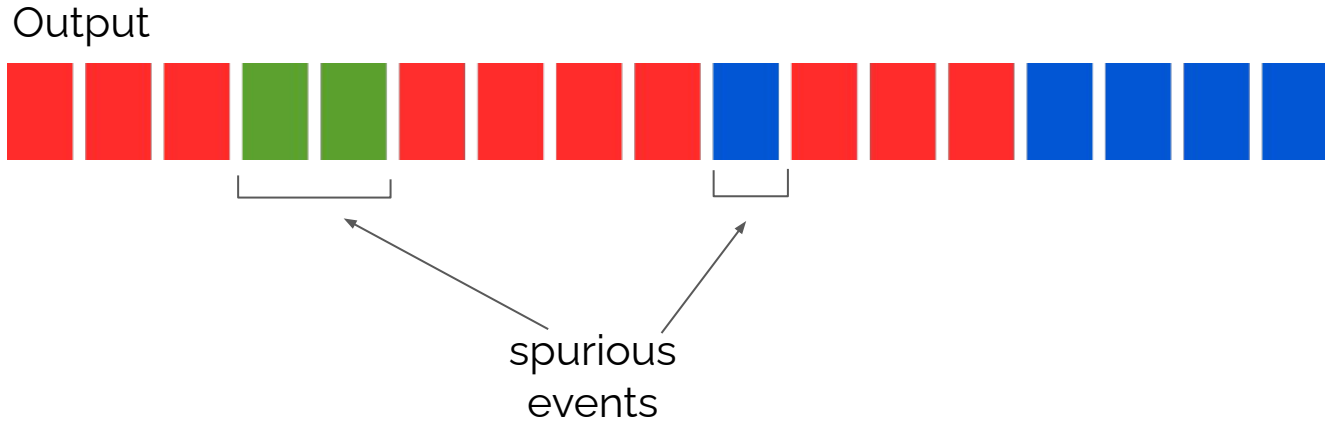
- sp_tool
- F1-score (samples and events)
- Events according to Hooge et al. [2]

[2] Hooge, Ignace TC, et al. "Is human classification by experienced untrained observers a gold standard in fixation detection?." *Behavior Research Methods* 50.5 (2018): 1864-1881.

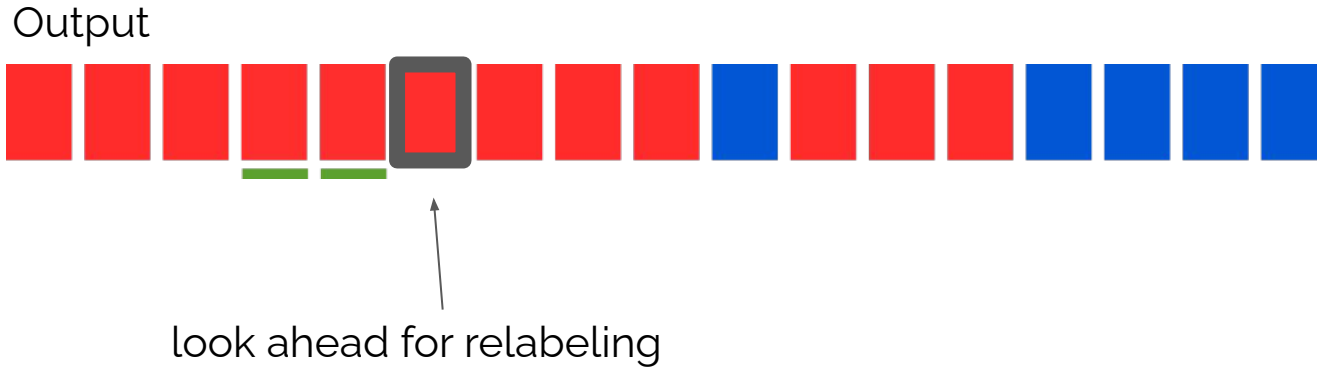


Knowledge-based filtering

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Knowledge-based filtering

Output filtered

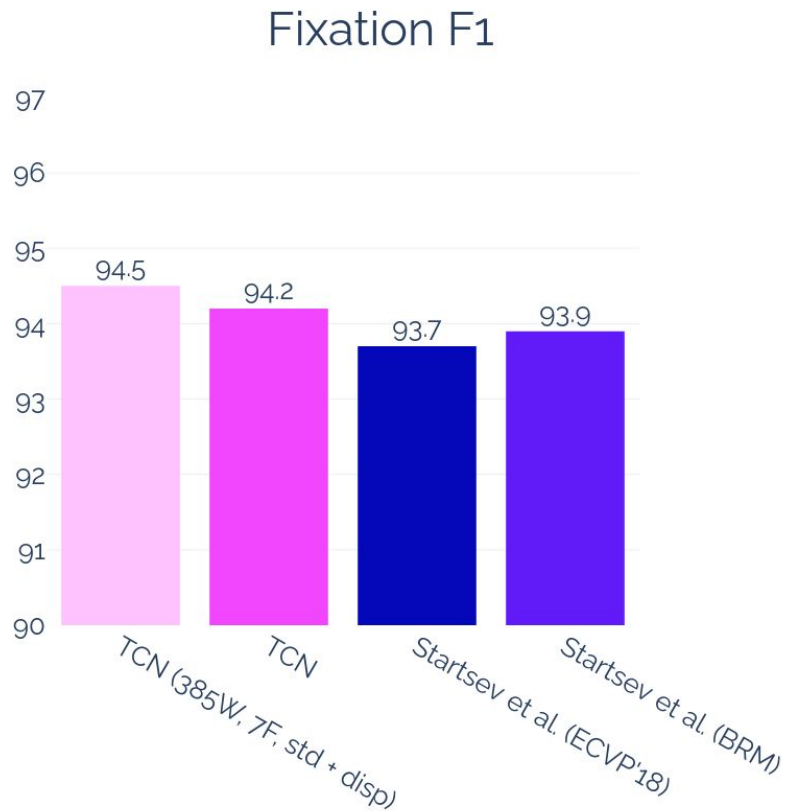




Results

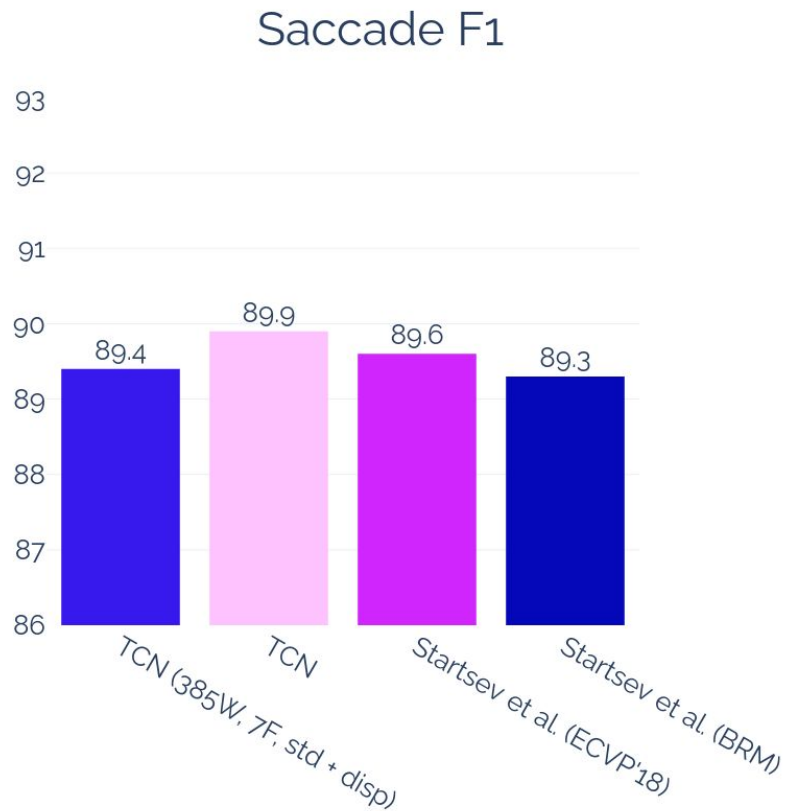
Results

- sample level



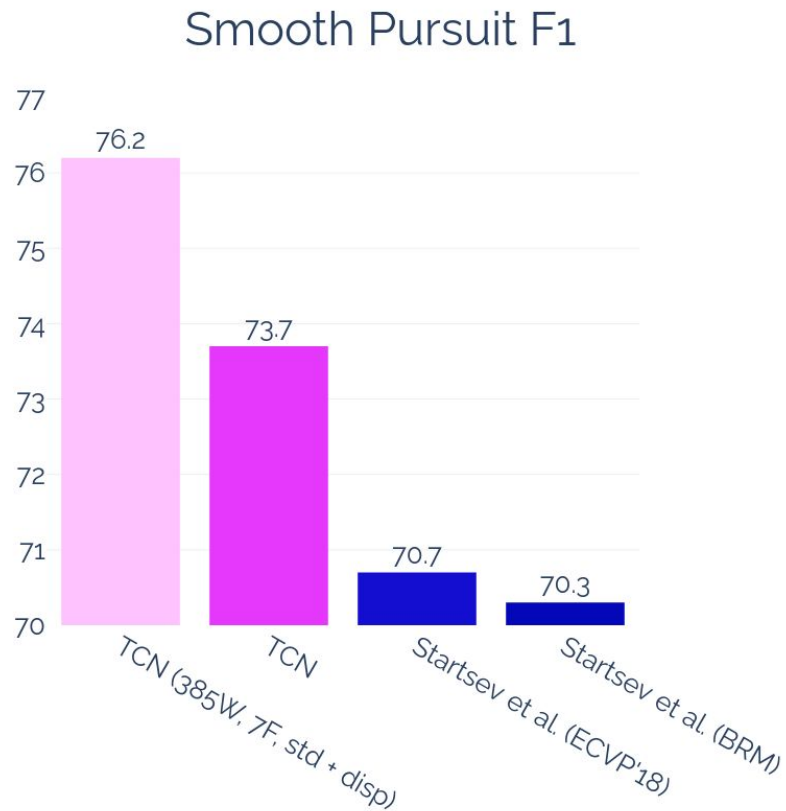
Results

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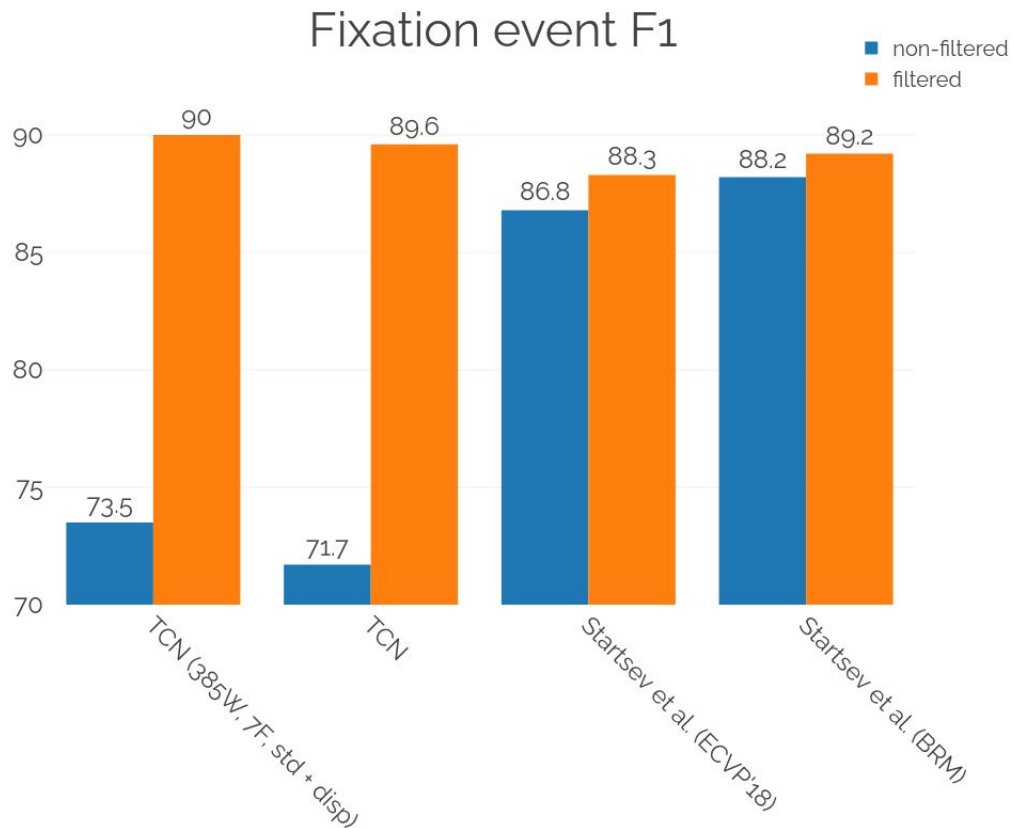
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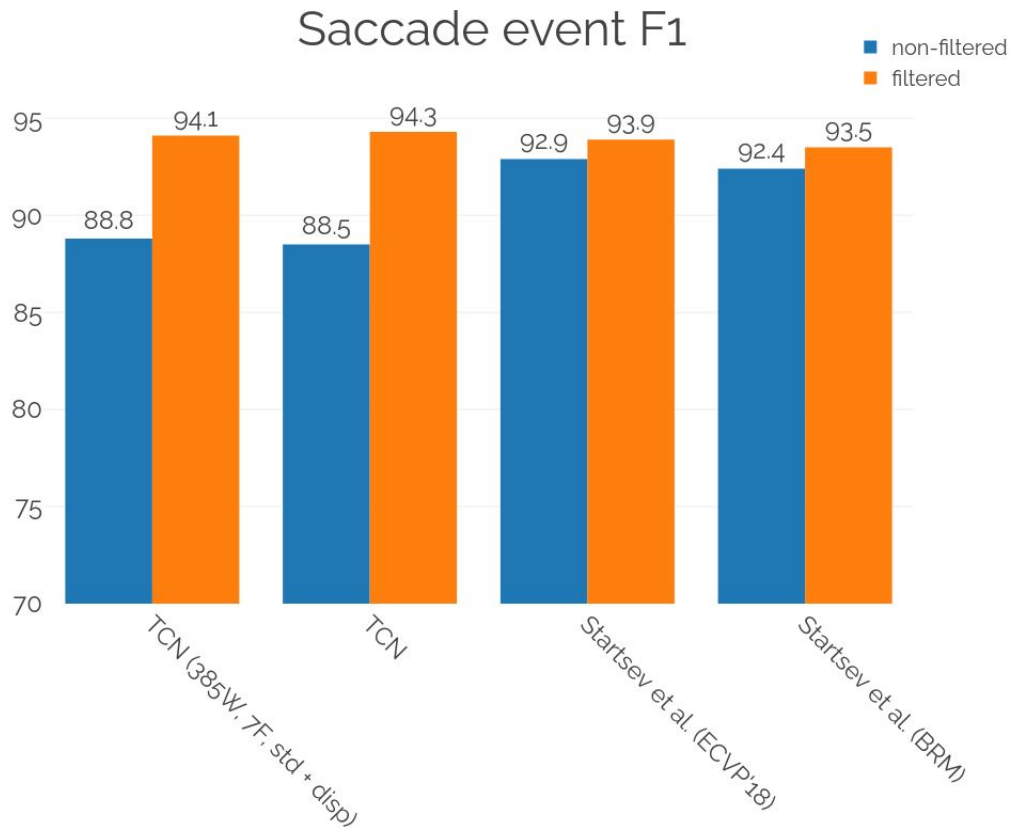
Results

- sample level
- event level



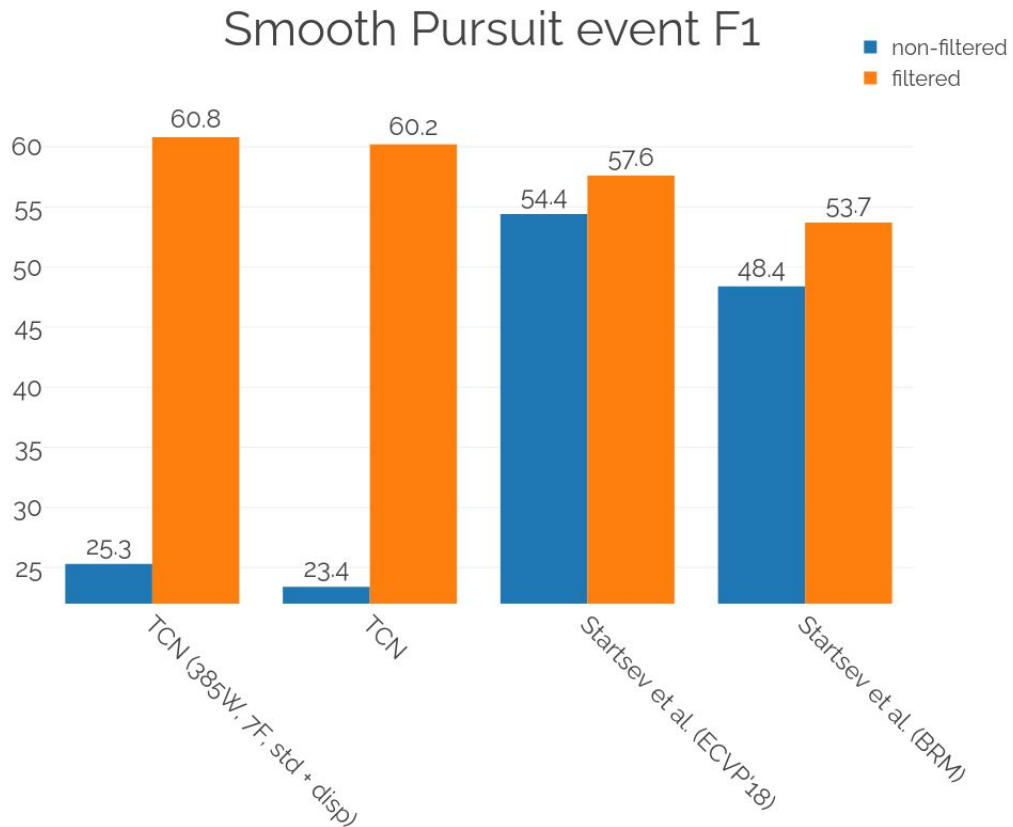
Results

- sample level
- event level



Results

- sample level
- event level



Results

- sample level
- event level
- exploratory

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feature space: +0.4% in SP F1

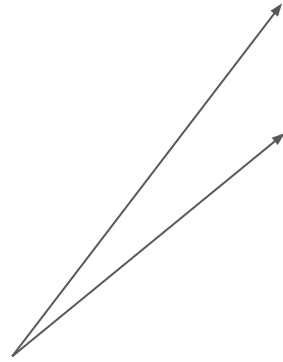


Results

- sample level
- event level
- exploratory

feature space: +0.4% in SP F1

feature scale: +0.9% in SP F1 (256 ms)



Results

- sample level
 - event level
 - exploratory
-
- feature space: +0.4% in SP F1
- feature scale: +0.9% in SP F1 (256 ms)
- window size: +1.4% in SP F1 (385 samples)
- The diagram consists of three arrows originating from the right side of the list items. The top arrow points from 'sample level' to 'feature space: +0.4% in SP F1'. The middle arrow points from 'event level' to 'feature scale: +0.9% in SP F1 (256 ms)'. The bottom arrow points from 'exploratory' to 'window size: +1.4% in SP F1 (385 samples)'.



Takeaways

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Q&A