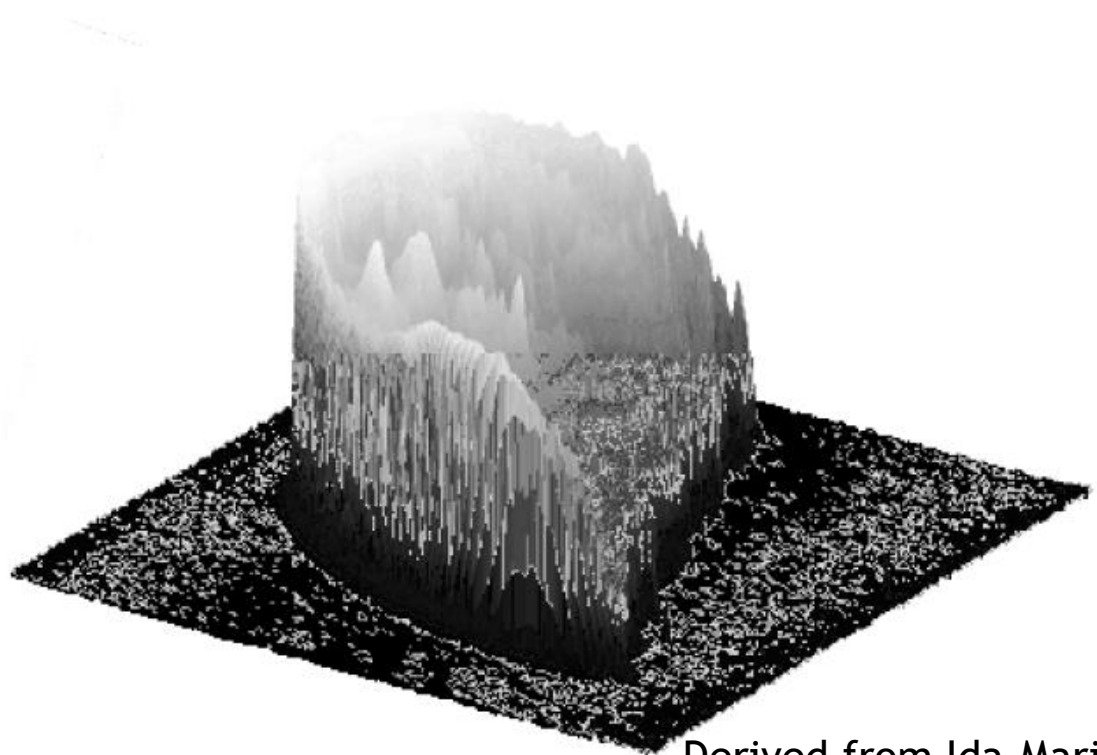


Mathematical Morphology

Grayscale Images and 3D

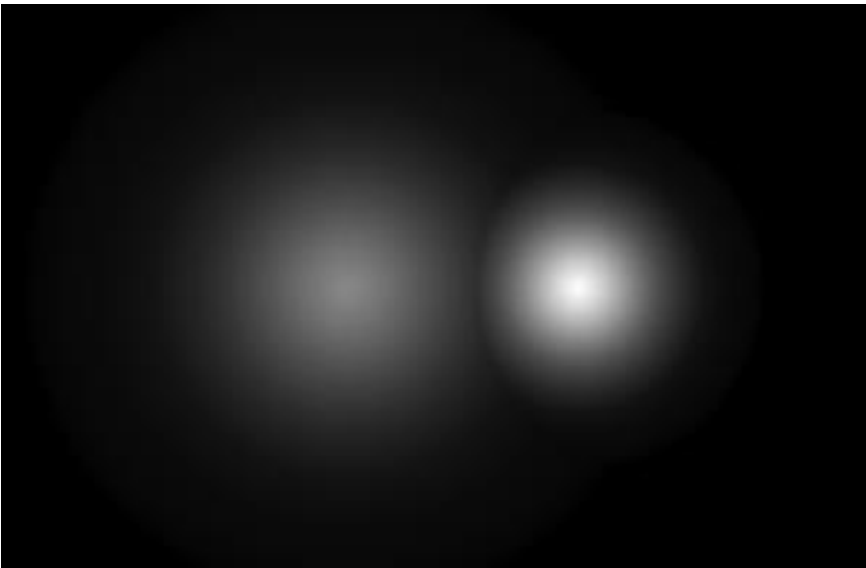
Extension to Grayscale Image

- ★ A 2D grayscale image is treated as a 3D solid in space – a landscape – whose height above the surface at a point is proportional to the brightness of the corresponding pixel.

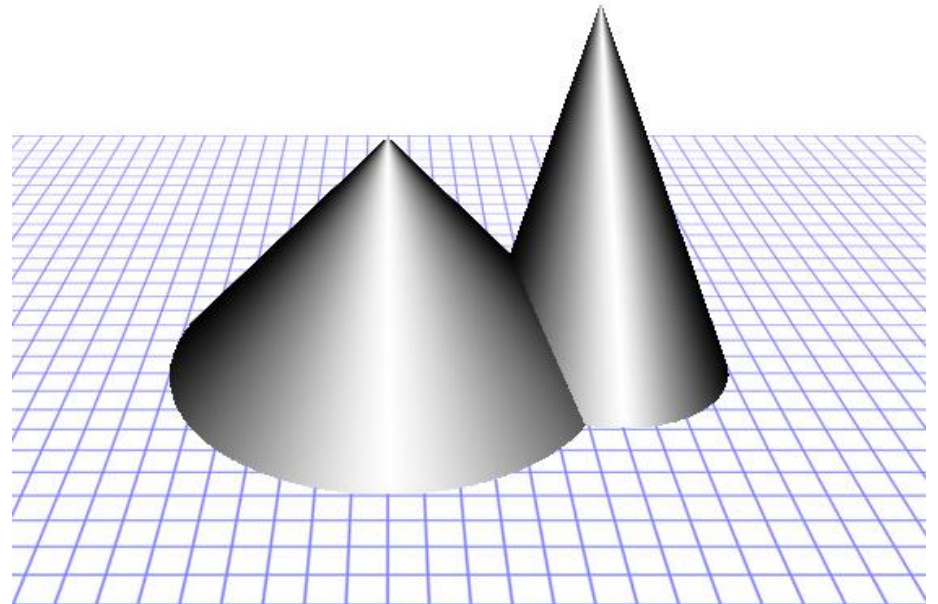


Derived from Ida-Maria Sintorn

Representation of Grayscale Images



image



landscape

Support of an Image



Image

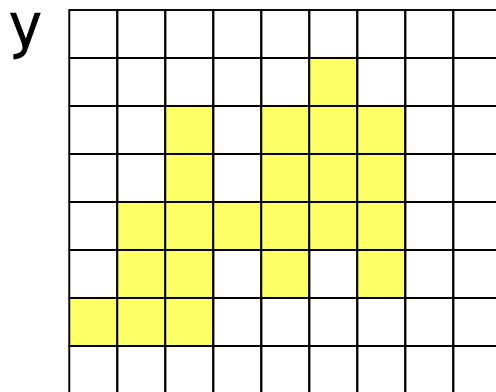
Support of Image \Rightarrow **Foreground F**

**Complement
of Support** : Background

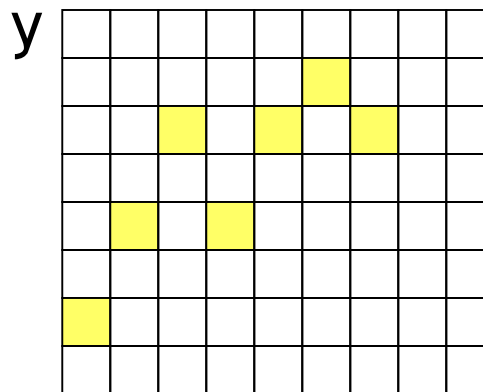


Umbra

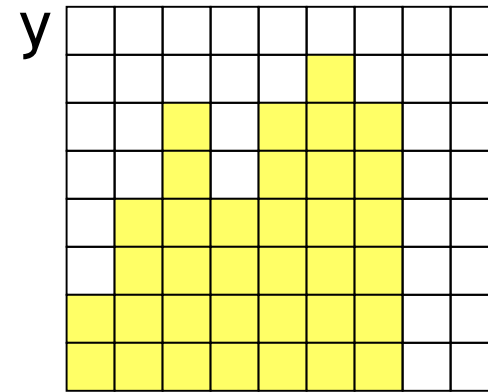
- ★ This part of mathematical morphology is an extension to multidimensional ‘images’ in particular to grey level and color images
- ★ $A \subseteq E^n$, $F \subseteq E^{n-1}$ (support of A), $x \in F$ (support element), $y \in E$ (intensity)
- ★ **Top of** a set A (example for $n=2$): $T[A](x) = \max \{ y \mid (x, y) \in A \}$
- ★ **Umbra** of f ($f: F \rightarrow E$): $U[f] = \{ (x, y) \in F \times E \mid y \leq f(x) \}$



Set A



Top of A



Umbra of A

Umbra - Properties

$$T[A] \subseteq A \subseteq U[A] \subseteq E^n$$

$$U[U[A]] \equiv U[A]$$

Umbra

- ★ For each function $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ it is possible to define an equivalent function $f: \mathbb{R}^3 \rightarrow \{0, 1\}$
 - ★ $g(x, y, z) = 1 \Leftrightarrow z \leq f(x, y) \Leftrightarrow z \in U[f(x, y)]$
 - ★ $g(x, y, z) = 0 \Leftrightarrow z > f(x, y) \Leftrightarrow z \notin U[f(x, y)]$
- ★ So the gray scale morphology is related to the mathematical morphology in 3D

Dilation for grey level images

★ $F, K \subseteq E^{n-1}$

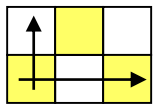
★ The dilation of image f and structural element k can be defined as:

$$f \oplus k = T\{U[f] \oplus U[k]\}$$

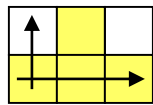
★ Tends to brighten the image, reduce dark regions

★ From the computational view point this operation is equivalent to a convolution

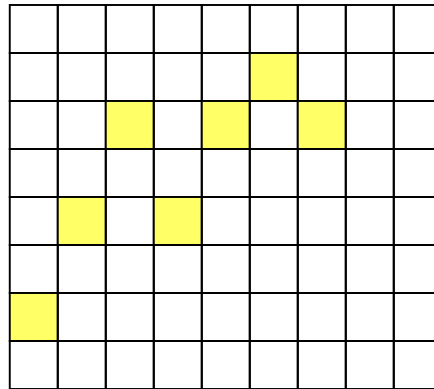
Dilation - Example



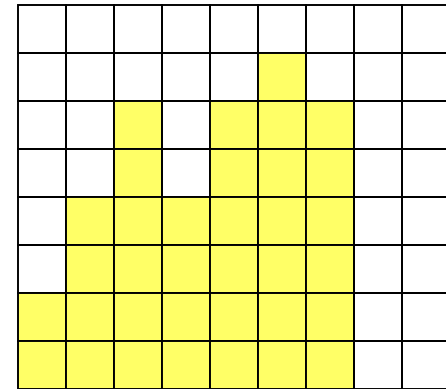
k



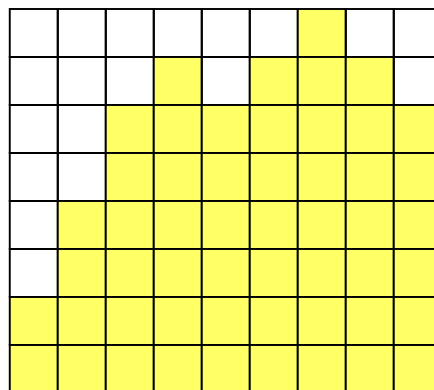
$U[k]$



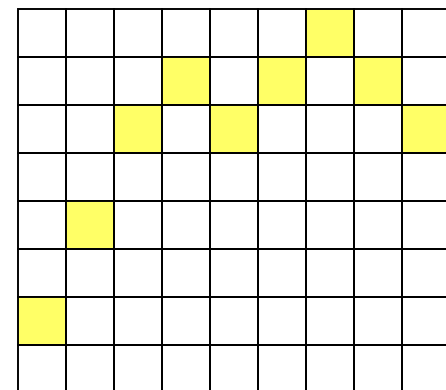
f



$U[f]$



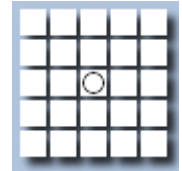
$U[f] \oplus U[k]$



$f \oplus k = T[U[f] \oplus U[k]]$ 9

Dilation - Example

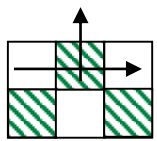
★ magick lena.png -morphology dilate square:2 dilate.png



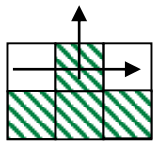
Grey scale erosion

- ★ $F, K \subseteq E^{n-1}$
- ★ The erosion of image f and structural element k can be defined as:
$$f \ominus k = T\{U[f] \ominus U[k]\}$$
- ★ Tends to darken the image, reduce bright regions
- ★ From the computational view point this operation is equivalent to a convolution

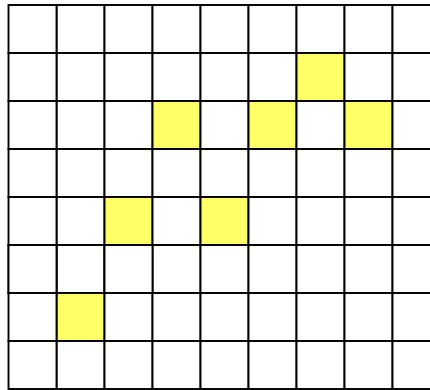
Erosion - Example



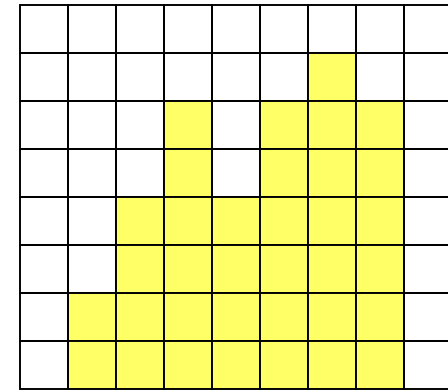
k



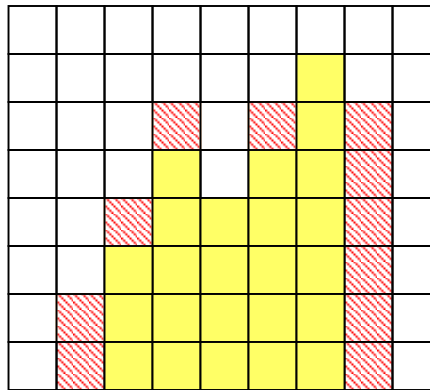
$U[k]$



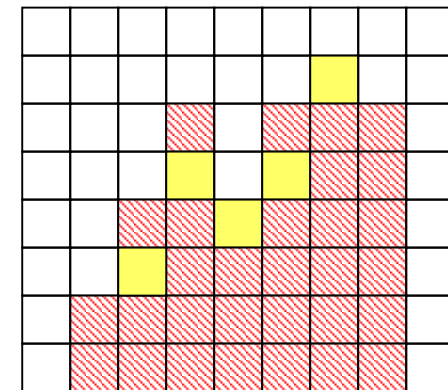
f



$U[f]$



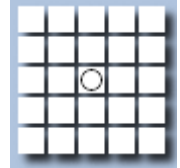
$U[f] \ominus U[k]$



$T\{U[f] \ominus U[k]\}$

Erosion - Example

★ magick lena.png -morphology erode square:2 erode.png

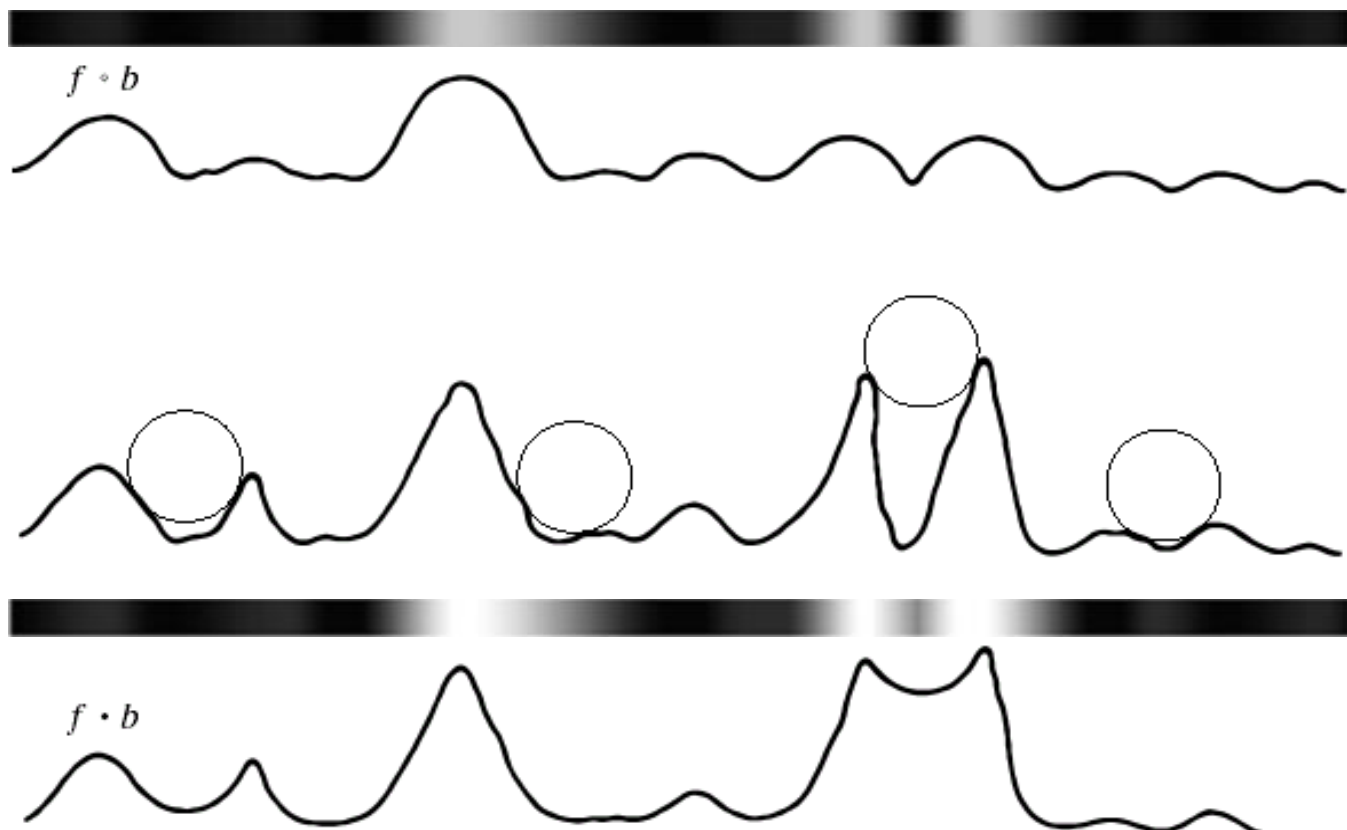
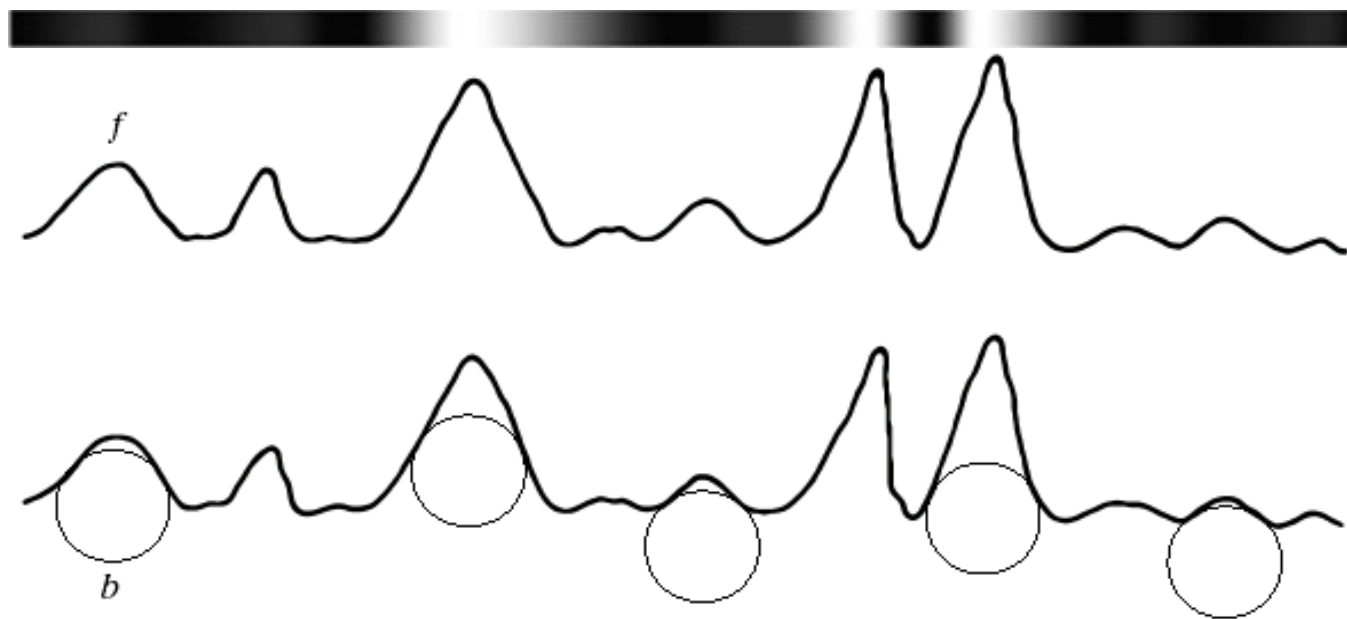


Opening and Closing

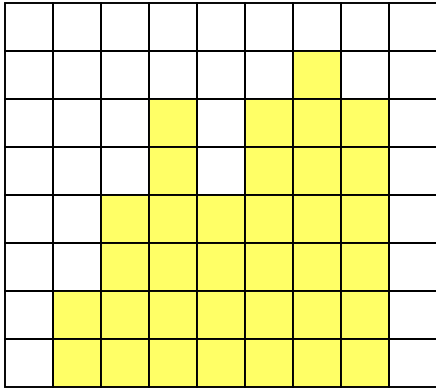
- ★ Opening and closing of an image $f(x,y)$ by a structuring element $b(x,y)$ have the same form as their binary counterpart:

$$f \circ b = (f \ominus b) \oplus b \qquad f \bullet b = (f \oplus b) \ominus b$$

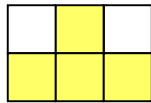
- ★ Geometric interpretation:
- ★ View the image as a 3-D surface map, and suppose we have a spherical structuring element.
 - ★ **Opening:** roll the sphere against the *underside* of the surface, and take the *highest points* reached by any part of the sphere. Opening reduces bright details eliminating curvatures smaller than the specified SE.
 - ★ **Closing:** roll the sphere *on top* of the surface, and take the *lowest points* reached by any part of the sphere. Closing reduces dark details eliminating curvatures smaller than the specified SE.
- ★ Opening and closing are used often in combination as morphological filters for image smoothing and noise removal.



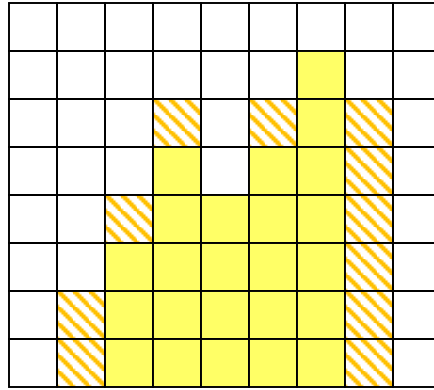
Opening - Example



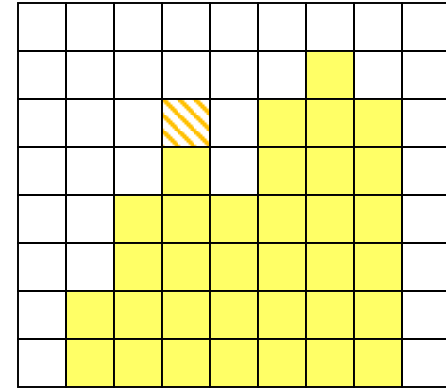
$U[A]$



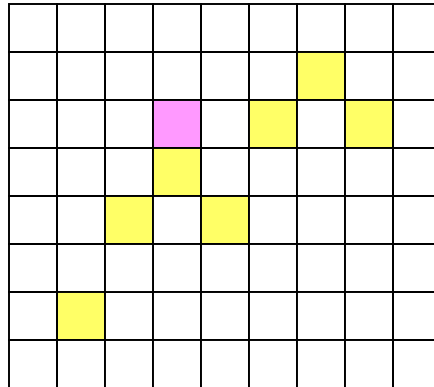
$U[k]$



$U[A] \ominus U[k]$



$U[A] \ominus U[k] \oplus U[k]$



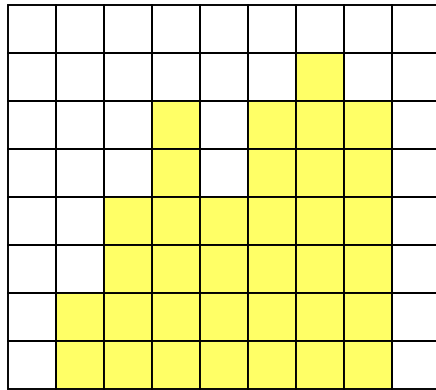
$A \circ k$

Opening - Example

- ★ magick lena.png -morphology open square:2 dilate.png



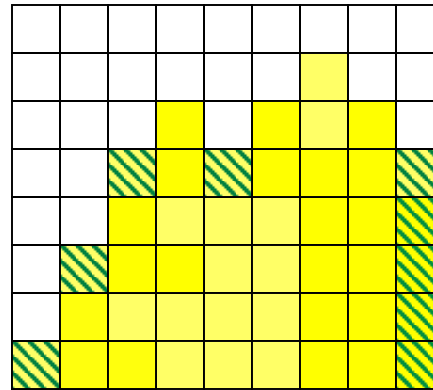
Closing - Example



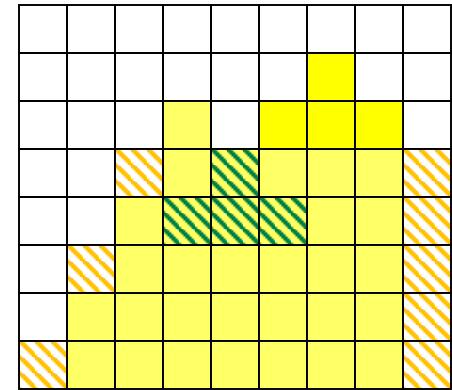
$U[A]$



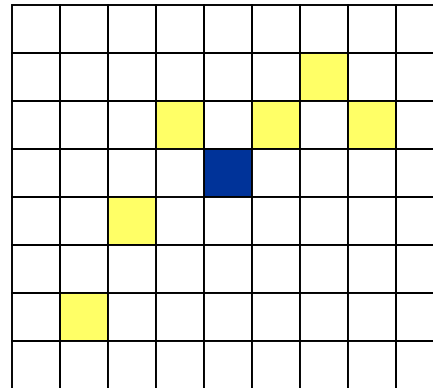
$U[k]$



$U[A] \oplus U[k]$



$[U[A] \oplus U[k]] \ominus U[k]$



$A \bullet k$

Closing - Example

- ★ magick lena.png -morphology close square:2 dilate.png



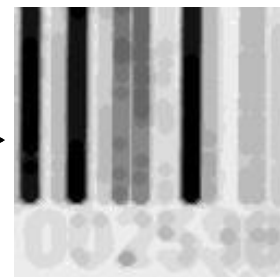
Opening vs Closing on Gray Value Images

- ★ Disk with radius 3 as structure element

- ★ **Opening**: all the thin white bands have disappeared, only the broad one remains



- ★ **Closing**: all the valleys where the structure element does not fit have been filled, only the three broad black bands remain



Opening vs Closing on Gray Value Images

- ★ 5x5 square structuring element



Closing

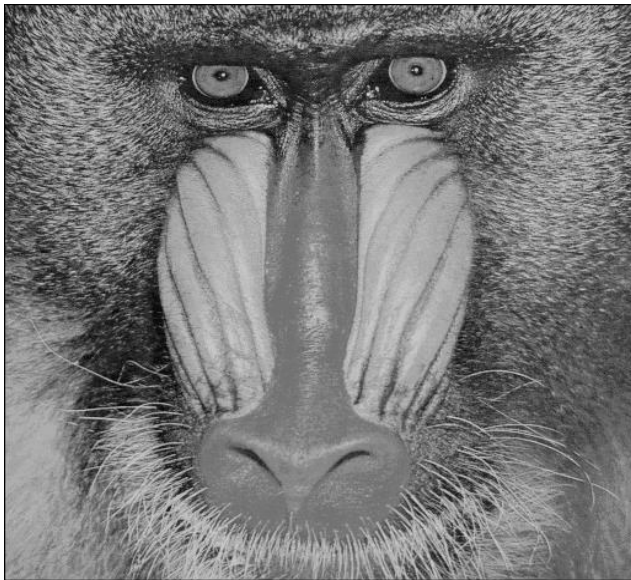


Opening

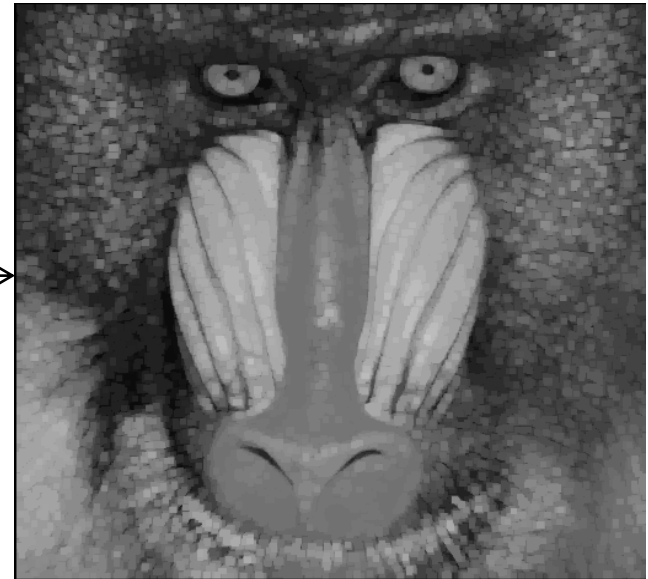


Opening vs Closing on Gray Value Images

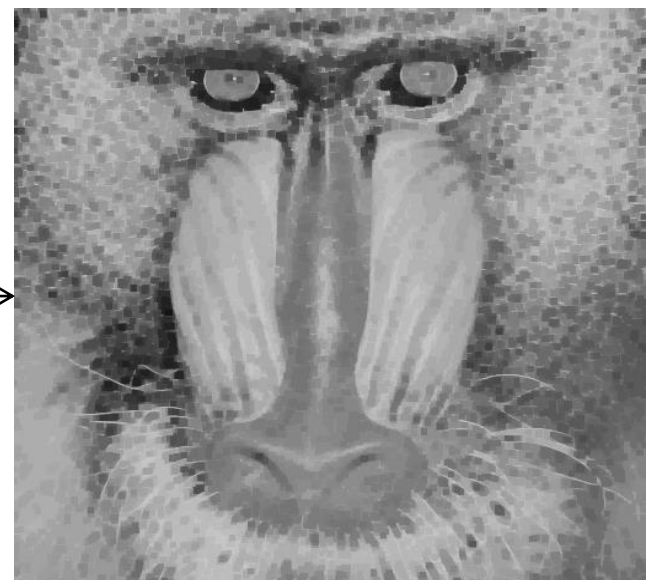
- ★ 5x5 square structuring element



Opening



Closing

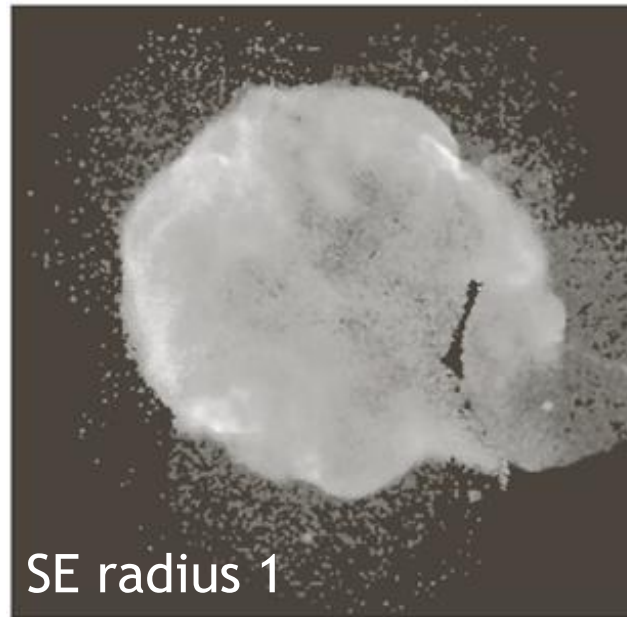
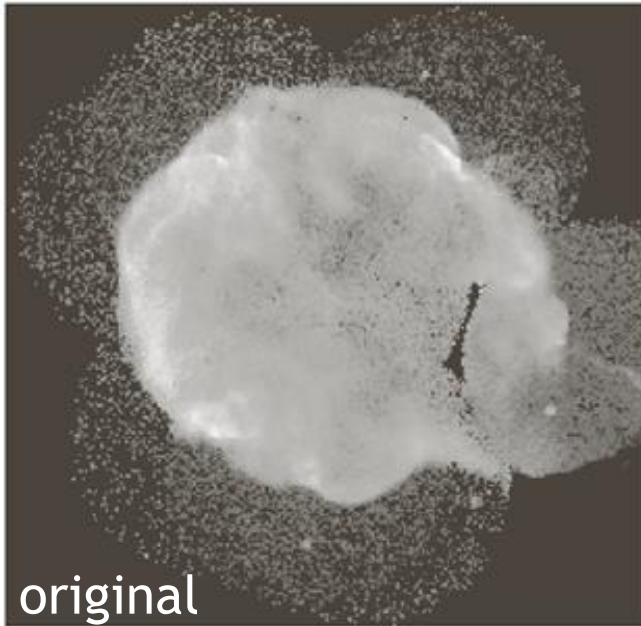


Morphological smoothing - Example

- ★ Opening followed by closing



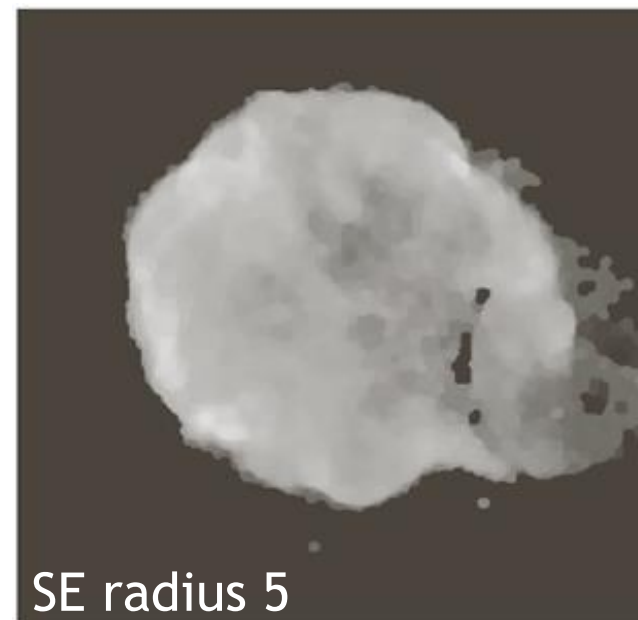
Morphological Smoothing: opening and closing



a	b
c	d

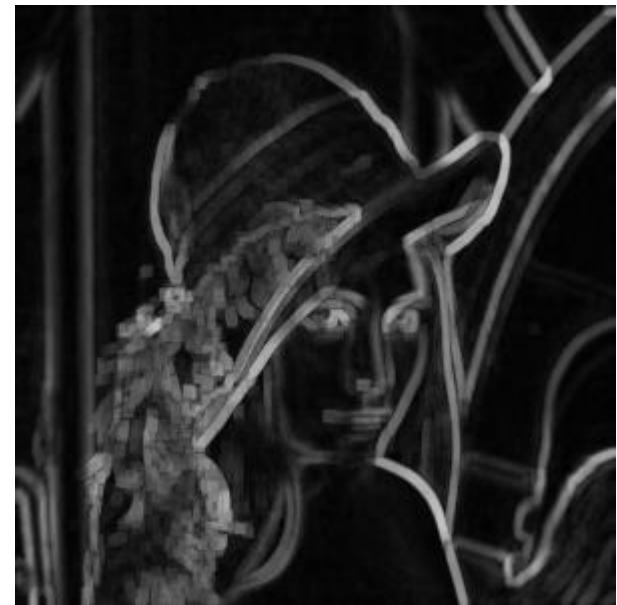
(a) 566×566 image of the Cygnus Loop supernova, taken in the X-ray band by NASA's Hubble Telescope. (b)–(d) Results of performing opening and closing sequences on the original image with disk structuring elements of radii, 1, 3, and 5, respectively. (Original image courtesy of NASA.)

Cygnus Loop supernova, taken by X-ray by NASA Hubble Telescope

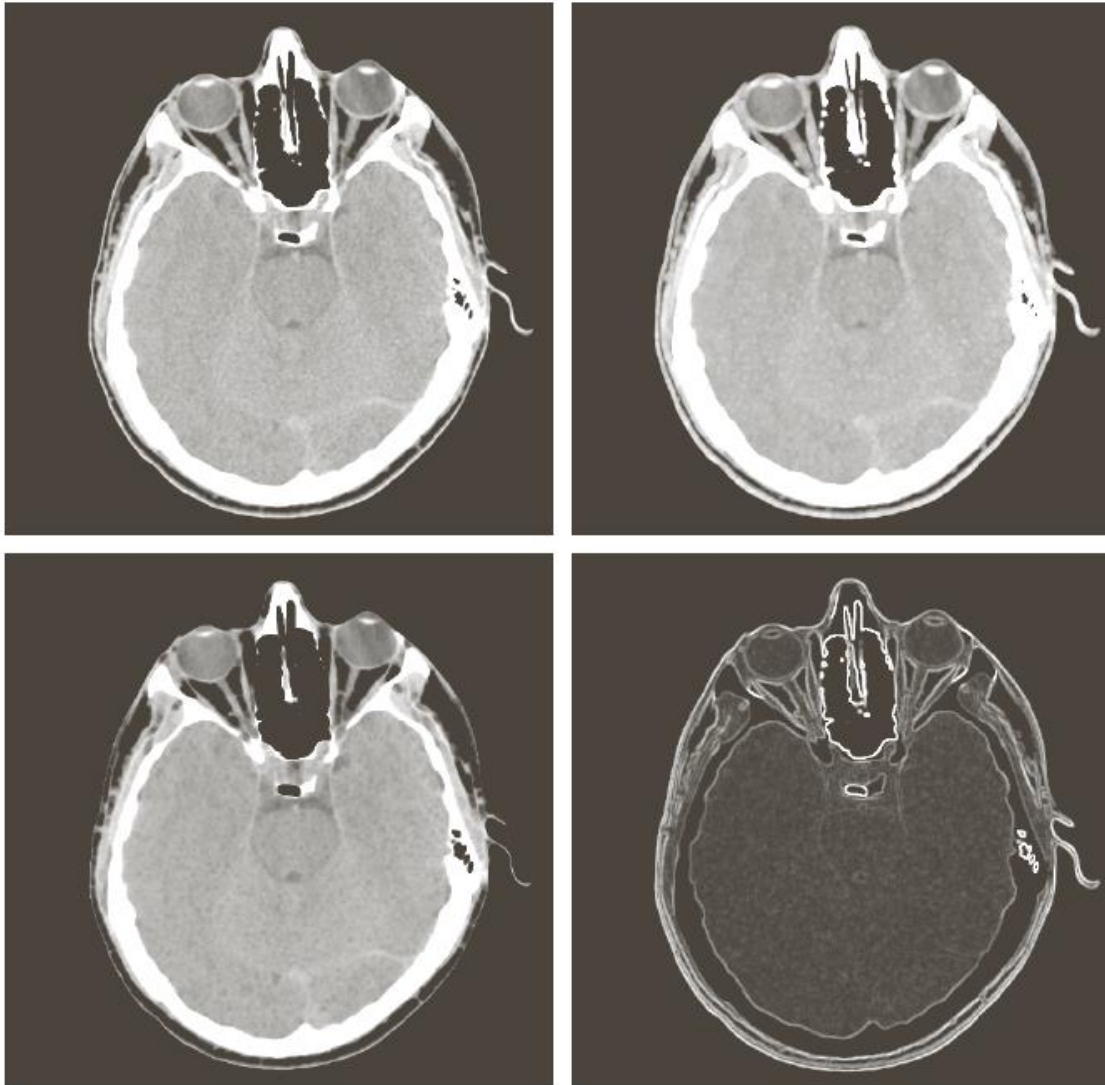


Morphological gradient - Example

- ★ Difference between dilation and erosion
- ★ magick lena.png -morphology edge square:2 edge.png
- ★ The edges are enhanced and the contribution of the homogeneous areas are suppressed, thus producing a “derivative-like” (gradient) effect.



Morphological Gradient



a	b
c	d

(a) 512×512 image of a head CT scan.
(b) Dilation.
(c) Erosion.
(d) Morphological gradient, computed as the difference between (b) and (c). (Original image courtesy of Dr. David R. Pickens, Vanderbilt University.)

Top-hat and Bottom-hat Transformations

- ★ The **top-hat** transformation of a grayscale image f is defined as **f minus its opening**:

$$T_{hat}(f) = f - (f \circ b)$$

- ★ The **bottom-hat** transformation of a grayscale image f is defined as its **closing minus f** :

$$B_{hat}(f) = (f \bullet b) - f$$

- ★ One of the principal applications of these transformations is in removing objects from an image by using structuring element in the opening or closing operation

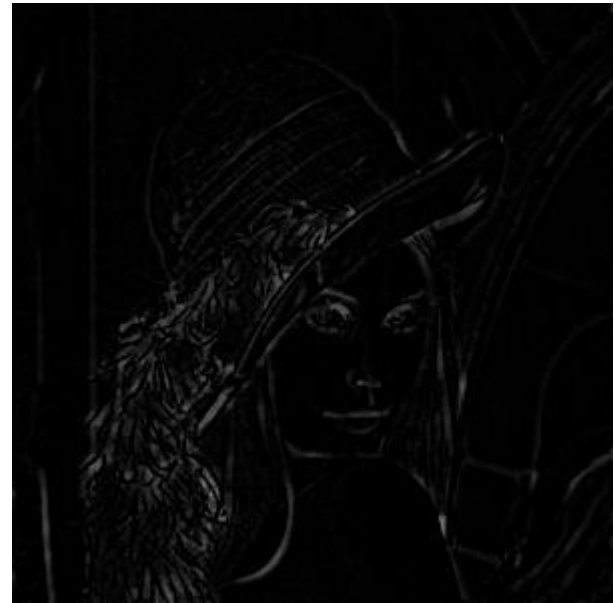
Top-hat transformation - Example

- ★ Difference between original and opening
- ★ `magick lena.png -morphology TopHat square:2 top.png`

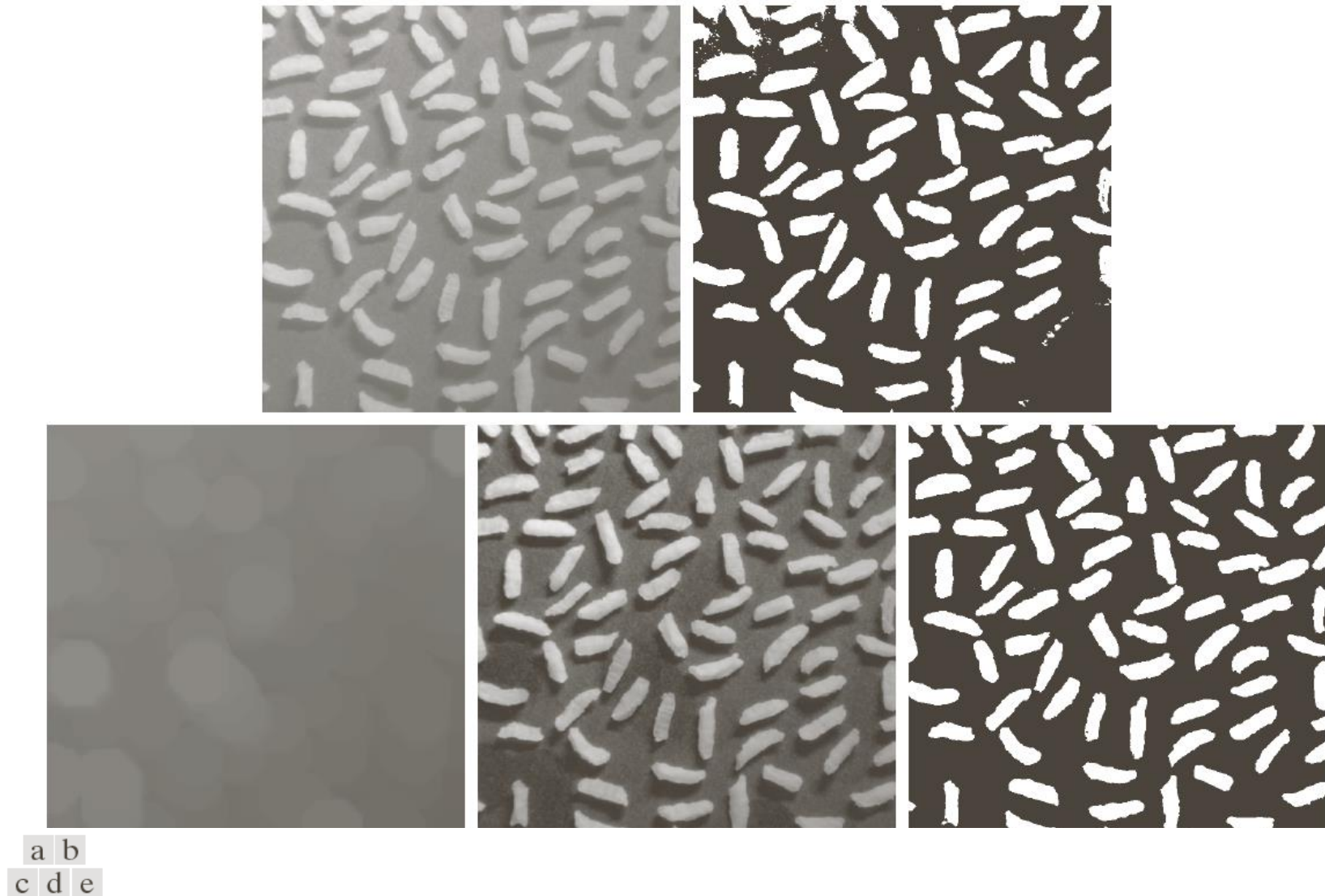


Bottom-hat transformation - Example

- ★ Difference between closing and original
- ★ `magick lena.png -morphology BottomHat square:2 bottom.png`



Example of Using Top-hat Transformation in Segmentation



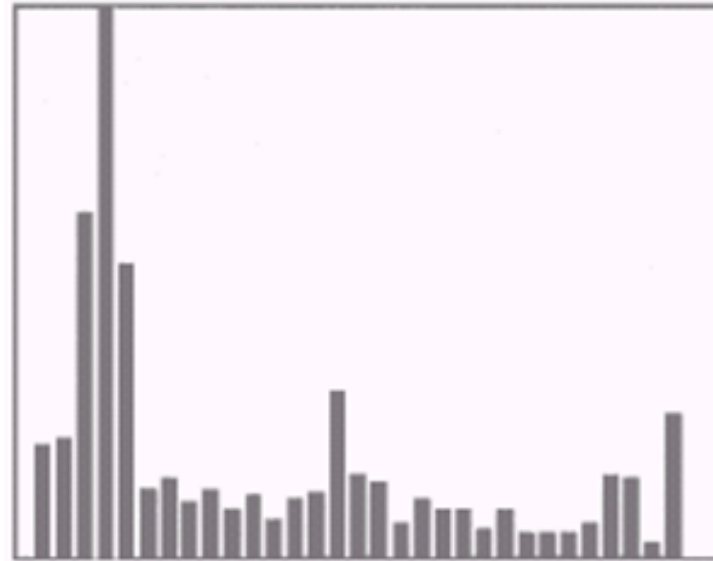
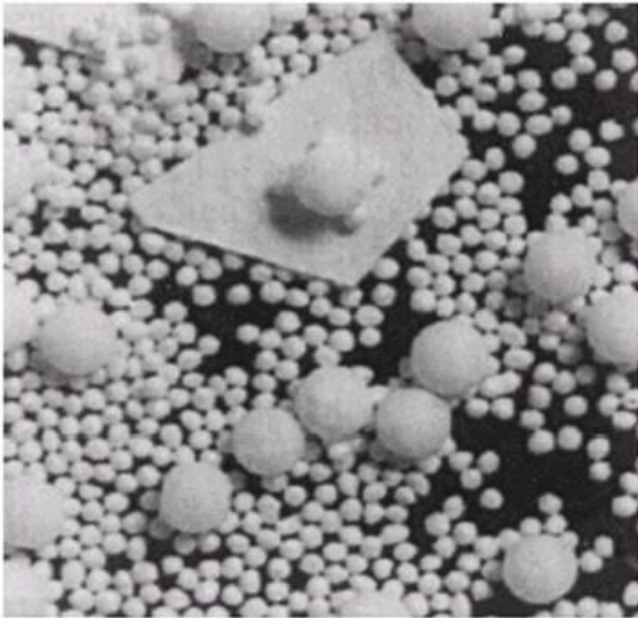
Using the top-hat transformation for *shading correction*. (a) Original image of size 600×600 pixels. (b) Thresholded image. (c) Image opened using a disk SE of radius 40. (d) Top-hat transformation (the image minus its opening). (e) Thresholded top-hat image.

Gonzales-Woods

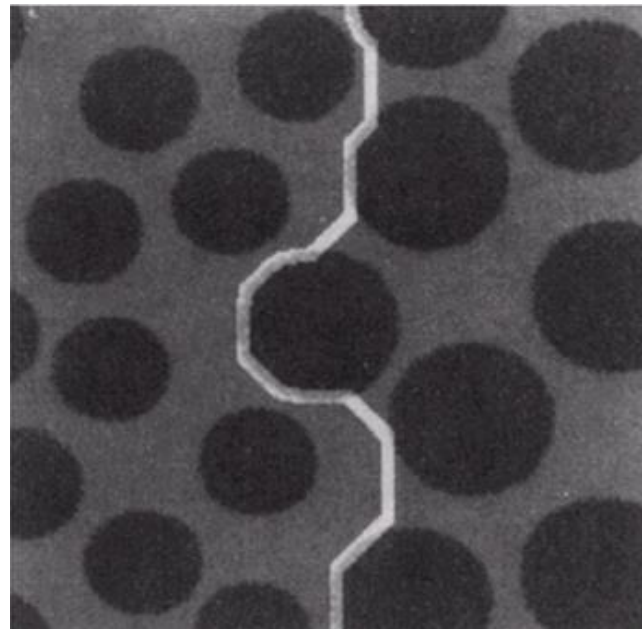
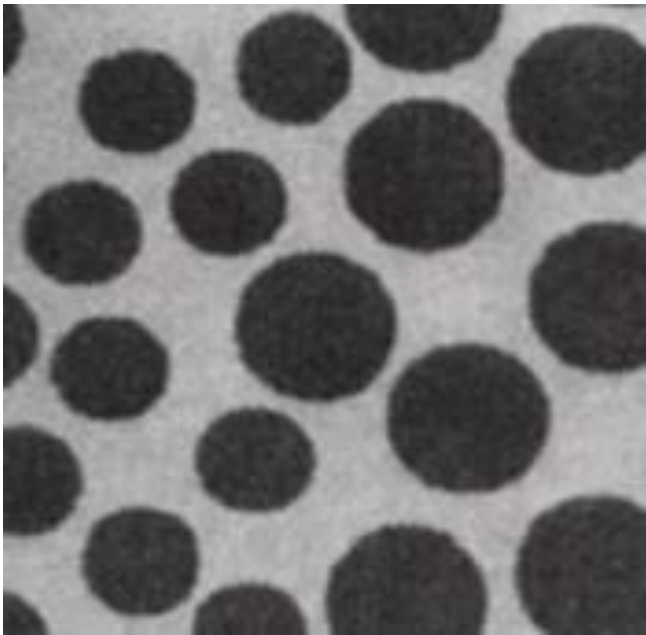
Granulometry

- ✦ **Granulometry** is a field that deals principally with **determining the size distribution of particles in an image.**
- ✦ a **morphological approach** to determine size distribution to construct a **histogram** of it is based on **opening** operations of particular size that have the most effect on regions of the input image that **contain particles of similar size.**
- ✦ For each opening, the sum (**surface area**) of the pixel values in the opening is computed
- ✦ This type of processing is **useful for describing regions with a predominant particle-like character.**

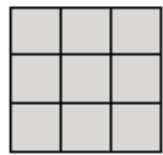
Granulometry and textural segmentation



Mr. A. Morris, Leica Cambridge, Ltd.

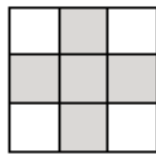


Summary



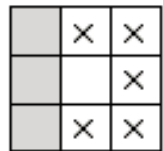
I

B



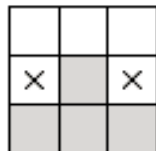
II

B



III

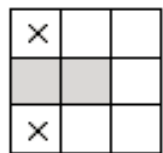
B^i $i = 1, 2, 3, 4$
(rotate 90°)



IV

B^i $i = 1, 2, \dots, 8$
(rotate 45°)

★ X's indicate
«don't care»
values



B^i $i = 1, 2, 3, 4$
(rotate 90°)



B^i $i = 5, 6, 7, 8$
(rotate 90°)

⏟
V

Summary

Operation	Equation	Comments
Translation	$(B)_z = \{w w = b + z, \text{ for } b \in B\}$	Translates the origin of B to point z .
Reflection	$\hat{B} = \{w w = -b, \text{ for } b \in B\}$	Reflects all elements of B about the origin of this set.
Complement	$A^c = \{w w \notin A\}$	Set of points not in A .
Difference	$A - B = \{w w \in A, w \notin B\}$ $= A \cap B^c$	Set of points that belong to A but not to B .
Dilation	$A \oplus B = \{z (\hat{B}_z) \cap A \neq \emptyset\}$	“Expands” the boundary of A . (I)
Erosion	$A \ominus B = \{z (B)_z \subseteq A\}$	“Contracts” the boundary of A . (I)
Opening	$A \circ B = (A \ominus B) \oplus B$	Smooths contours, breaks narrow isthmuses, and eliminates small islands and sharp peaks. (I)

(Continued)

Summary

Operation	Equation	Comments
Closing	$A \bullet B = (A \oplus B) \ominus B$	Smooths contours, fuses narrow breaks and long thin gulfs, and eliminates small holes. (I)
Hit-or-miss transform	$A \otimes B = (A \ominus B_1) \cap (A^c \ominus B_2)$ $= (A \ominus B_1) - (A \oplus \hat{B}_2)$	The set of points (coordinates) at which, simultaneously, B_1 found a match ("hit") in A and B_2 found a match in A^c
Boundary extraction	$\beta(A) = A - (A \ominus B)$	Set of points on the boundary of set A . (I)
Hole filling	$X_k = (X_{k-1} \oplus B) \cap A^c$; $k = 1, 2, 3, \dots$	Fills holes in A ; X_0 = array of 0s with a 1 in each hole. (II)
Connected components	$X_k = (X_{k-1} \oplus B) \cap A$; $k = 1, 2, 3, \dots$	Finds connected components in A ; X_0 = array of 0s with a 1 in each connected component. (I)

(Continued)
Gonzales-Woods

Summary

Operation	Equation	Comments
Convex hull	$X_k^i = (X_{k-1}^i \otimes B^i) \cup A;$ $i = 1, 2, 3, 4;$ $k = 1, 2, 3, \dots;$ $X_0^i = A; \text{ and}$ $D^i = X_{\text{conv}}^i$	Finds the convex hull $C(A)$ of set A , where "conv" indicates convergence in the sense that $X_k^i = X_{k-1}^i$. (III)
Thinning	$A \otimes B = A - (A \odot B)$ $= A \cap (A \odot B)^c$ $A \otimes \{B\} =$ $((\dots((A \otimes B^1) \otimes B^2) \dots) \otimes B^n)$ $\{B\} = \{B^1, B^2, B^3, \dots, B^n\}$	Thins set A . The first two equations give the basic definition of thinning. The last equations denote thinning by a sequence of structuring elements. This method is normally used in practice. (IV)
Thickening	$A \odot B = A \cup (A \otimes B)$ $A \odot \{B\} =$ $((\dots(A \odot B^1) \odot B^2 \dots) \odot B^n)$ \dots	Thickens set A . (See preceding comments on sequences of structuring elements.) Uses IV with 0s and 1s reversed.

Summary

Operation	Equation	Comments
Skeletons	$S(A) = \bigcup_{k=0}^K S_k(A)$ $S_k(A) = \bigcup_{k=0}^K \{ (A \ominus kB) - [(A \ominus kB) \circ B] \}$ <p>Reconstruction of A:</p> $A = \bigcup_{k=0}^K (S_k(A) \oplus kB)$	<p>Finds the skeleton $S(A)$ of set A. The last equation indicates that A can be reconstructed from its skeleton subsets $S_k(A)$. In all three equations, K is the value of the iterative step after which the set A erodes to the empty set. The notation $(A \ominus kB)$ denotes the kth iteration of successive erosions of A by B. (I)</p>
Pruning	$X_1 = A \otimes \{B\}$ $X_2 = \bigcup_{k=1}^8 (X_1 \oplus B^k)$ $X_3 = (X_2 \oplus H) \cap A$ $X_4 = X_1 \cup X_3$	<p>X_4 is the result of pruning set A. The number of times that the first equation is applied to obtain X_1 must be specified. Structuring elements V are used for the first two equations. In the third equation H denotes structuring element I.</p>

Operation	Description
<code>bothat</code>	“Bottom-hat” operation using a 3×3 structuring element; use <code>imbothat</code> (see Section 9.6.2) for other structuring elements.
<code>bridge</code>	Connect pixels separated by single-pixel gaps.
<code>clean</code>	Remove isolated foreground pixels.
<code>close</code>	Closing using a 3×3 structuring element; use <code>imclose</code> for other structuring elements.
<code>diag</code>	Fill in around diagonally connected foreground pixels.
<code>dilate</code>	Dilation using a 3×3 structuring element; use <code>imdilate</code> for other structuring elements.
<code>erode</code>	Erosion using a 3×3 structuring element; use <code>imerode</code> for other structuring elements.
<code>fill</code>	Fill in single-pixel “holes” (background pixels surrounded by foreground pixels); use <code>imfill</code> (see Section 11.1.2) to fill in larger holes.
<code>hbreak</code>	Remove H-connected foreground pixels.
<code>majority</code>	Make pixel p a foreground pixel if at least five pixels in $N_8(p)$ (see Section 9.4) are foreground pixels; otherwise make p a background pixel.
<code>open</code>	Opening using a 3×3 structuring element; use function <code>imopen</code> for other structuring elements.
<code>remove</code>	Remove “interior” pixels (foreground pixels that have no background neighbors).
<code>shrink</code>	Shrink objects with no holes to points; shrink objects with holes to rings.
<code>skel</code>	Skeletonize an image.
<code>spur</code>	Remove spur pixels.
<code>thicken</code>	Thicken objects without joining disconnected 1s.
<code>thin</code>	Thin objects without holes to minimally connected strokes; thin objects with holes to rings.
<code>tophat</code>	“Top-hat” operation using a 3×3 structuring element; use <code>imtophat</code> (see Section 9.6.2) for other structuring elements.