

# *Artificial Intelligence*

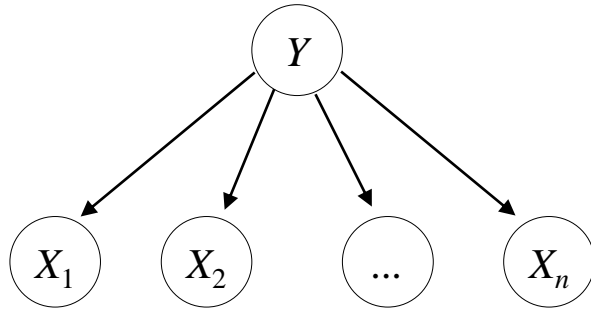
Probabilistic reasoning:  
*supervised learning*  
*and numerical optimization*

Marco Piastra

# Prologue: Logistic Regression

# Graphical Models Redux

## ■ Naïve Bayesian Classifier

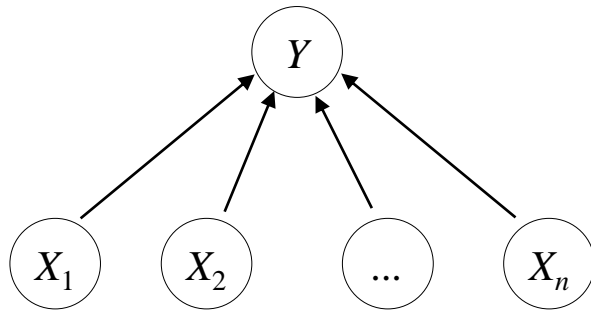


$$P(Y, X_1, \dots, X_n) = P(Y) \prod_{i=1}^n P(X_i|Y)$$

A 'generative' model

Classification  $\frac{P(Y = 1)}{P(Y = 0)} \prod_{i=1}^n \frac{P(X_i|Y = 1)}{P(X_i|Y = 0)} > \lambda$

## ■ Alternative model\*



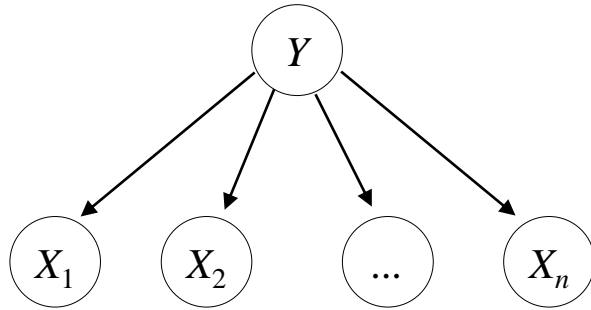
Just reverting the arrows ...

$$P(Y, X_1, \dots, X_n) = P(Y|X_1, \dots, X_n) \prod_{i=1}^n P(X_i)$$

Classification  $\frac{P(Y = 1|X_1, \dots, X_n)}{P(Y = 0|X_1, \dots, X_n)} > \lambda$

# Graphical Models Redux

## ■ Naïve Bayesian Classifier

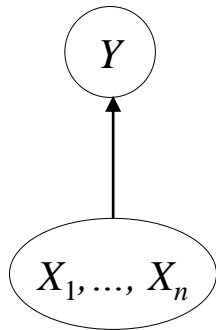


$$P(Y, X_1, \dots, X_n) = P(Y) \prod_{i=1}^n P(X_i | Y)$$

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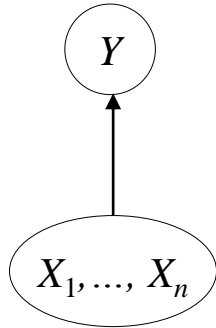
$$P(Y, X_1, \dots, X_n) = P(Y | X_1, \dots, X_n) P(X_1, \dots, X_n)$$

$$\text{Classification } \frac{P(Y = 1 | X_1, \dots, X_n)}{P(Y = 0 | X_1, \dots, X_n)} > \lambda$$

Removing any independence hypotheses ...

# Graphical Models Redux

## ■ Alternative model\*



$$P(Y, X_1, \dots, X_n) = P(Y|X_1, \dots, X_n)P(X_1, \dots, X_n)$$

Classification  $\frac{P(Y = 1|X_1, \dots, X_n)}{P(Y = 0|X_1, \dots, X_n)} > \lambda$

*It may sound promising...*

No counter-intuitive independence assumptions (*as compared to Naïve Bayesian Classifier*)

It is enough to learn one conditional distribution  $P(Y|X_1, \dots, X_n)$

The MLE is the relative frequency

$$P(Y = y|X_1 = x_1, \dots, X_n = x_n) = \frac{N_{Y=y, X_1=x_1, \dots, X_n=x_n}}{N_{X_1=x_1, \dots, X_n=x_n}}$$

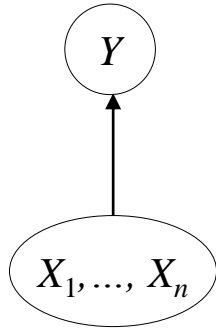
*However...*

$2^n$  probabilities will have to be learnt

Hardly any real-world dataset will contain all possible combinations ...

# Logistic Regression

## ■ Graphical Model



$$P(Y, X_1, \dots, X_n) = P(Y|X_1, \dots, X_n)P(X_1, \dots, X_n)$$

$$\text{Classification} \quad \frac{P(Y = 1|X_1, \dots, X_n)}{P(Y = 0|X_1, \dots, X_n)} > \lambda$$

For convenience, define:

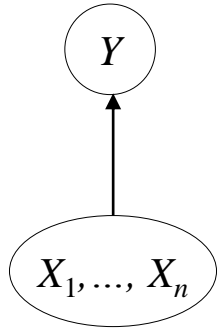
$$p(\mathbf{x}) := P(Y = 1|X_1 = x_1, \dots, X_n = x_n) \quad \text{where} \quad \mathbf{x} := \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \quad \text{i.e. a vector}$$

$$\frac{P(Y = 1|X_1 = x_1, \dots, X_n = x_n)}{P(Y = 0|X_1 = x_1, \dots, X_n = x_n)} = \frac{p(\mathbf{x})}{1 - p(\mathbf{x})}$$

OK. How can we define  $p(\mathbf{x})$  then?

# Logistic Regression

## ■ Graphical Model



$$P(Y, X_1, \dots, X_n) = P(Y|X_1, \dots, X_n)P(X_1, \dots, X_n)$$

$$p(\mathbf{x}) := P(Y = 1|X_1 = x_1, \dots, X_n = x_n)$$

$$\text{Classification } \frac{p(\mathbf{x})}{1 - p(\mathbf{x})} > \lambda$$

Logit transform:

$$\log \frac{p(\mathbf{x})}{1 - p(\mathbf{x})} = f(\mathbf{x}) \quad \Rightarrow \quad p(\mathbf{x}) = \frac{e^{f(\mathbf{x})}}{1 + e^{f(\mathbf{x})}} = \frac{1}{1 + e^{-f(\mathbf{x})}} = \sigma(f(\mathbf{x}))$$

|  
the sigmoid  
function

Assume  $f(\mathbf{x})$  linear

$$f(\mathbf{x}) := \mathbf{w}\mathbf{x} + b$$

/ a vector of parameters  
/ scalar product of vectors

$$\Rightarrow p(\mathbf{x}) = \frac{1}{1 + e^{-(\mathbf{w}\mathbf{x} + b)}}$$

Logistic Regression  
(i.e. a parametric distribution)

$$\theta := \{\mathbf{w}, b\}$$

# Logistic Regression

## ■ Maximum Likelihood Estimation

Dataset

$$D = \{ \langle \mathbf{x}^{(i)}, y^{(i)} \rangle \}_{i=1}^N$$

Conditional probability

$$P(Y = 1 | \mathbf{x}) = p(\mathbf{x}) = \frac{1}{1 + e^{-(\mathbf{w}\mathbf{x}+b)}}$$

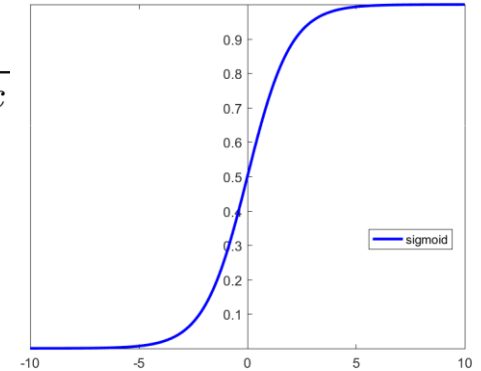
Likelihood

$$L(D, \theta) := \prod_{i=1}^N p(\mathbf{x}^{(i)})^{y^{(i)}} (1 - p(\mathbf{x}^{(i)}))^{(1-y^{(i)})}$$

Log-likelihood

$$\begin{aligned} l(D, \theta) &:= \log l(D, \theta) = \log \prod_{i=1}^N p(\mathbf{x}^{(i)})^{y^{(i)}} (1 - p(\mathbf{x}^{(i)}))^{(1-y^{(i)})} \\ &= \sum_{i=1}^N y^{(i)} \log p(\mathbf{x}^{(i)}) + (1 - y^{(i)}) \log(1 - p(\mathbf{x}^{(i)})) \end{aligned}$$

$$\frac{1}{1 + e^{-x}}$$



A 'discriminative' model

This is a product of conditional probabilities (IID data)



# Logistic Regression

## ■ Maximum Likelihood Estimation

Log-likelihood

$$\begin{aligned}l(D, \theta) &= \sum_{i=1}^N y^{(i)} \log p(\mathbf{x}^{(i)}) + (1 - y^{(i)}) \log(1 - p(\mathbf{x}^{(i)})) \\&= \sum_{i=1}^N \log(1 - p(\mathbf{x}^{(i)})) + \sum_{i=1}^N y^{(i)} \log \frac{p(\mathbf{x}^{(i)})}{1 - p(\mathbf{x}^{(i)})} \\&= \sum_{i=1}^N \log(1 - p(\mathbf{x}^{(i)})) + \sum_{i=1}^N y^{(i)} (\mathbf{w}\mathbf{x}^{(i)} + b) \\&= \sum_{i=1}^N -\log(1 + e^{\mathbf{w}\mathbf{x}^{(i)} + b}) + \sum_{i=1}^N y^{(i)} (\mathbf{w}\mathbf{x}^{(i)} + b)\end{aligned}$$

MLE (a.k.a. Maximum Conditional Likelihood Estimator MCLE in this case)

$$\theta^* := \operatorname{argmax}_{\theta} l(D, \theta) = \operatorname{argmin}_{\theta} nl(D, \theta)$$

where

$$\text{negative log-likelihood} \quad nl(D, \theta) := -l(D, \theta)$$

$nl(D, \theta)$  is convex for  $\theta$  but it cannot be minimized analytically ...

# Gradient Descent *(and all that)*

# Gradient Descent (GD): intuition

## ■ Objective

Turn this into a minimization problem

$$\theta^* := \operatorname{argmin}_{\theta} nl(D, \theta)$$

negative log-likelihood  $nl(D, \theta) := -l(D, \theta)$

## ■ Iterative method

Step in the method

1. Initialize  $\theta^{(0)}$  at random
2. Update  $\theta^{(t)} = \theta^{(t-1)} - \eta \nabla_{\theta} nl(D, \theta^{(t-1)})$
3. Unless some termination criterion has been met, go back to step 2.

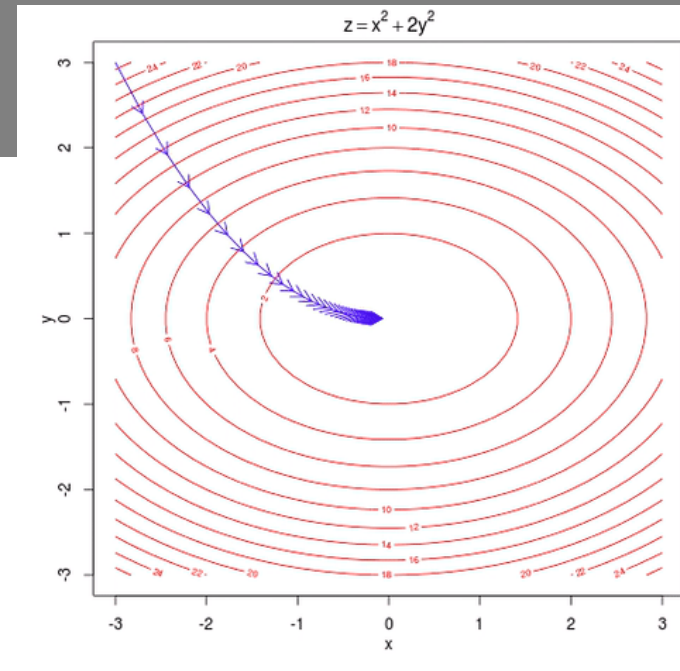
*In detail*

$$\nabla_{\theta} nl(D, \theta) := \sum_D \nabla_{\theta} nl(\mathbf{x}^{(i)}, y^{(i)}, \theta)$$

The gradient of the loss over the dataset  $D$  is the sum of gradients over each data item

$$\eta \ll 1$$

A learning rate, it is arbitrary (i.e. an *hyperparameter*)



# Gradient Descent (GD): convergence

## ■ Convergence

When  $nl(D, \theta)$  is *convex, derivable, and Lipschitz continuous*, that is

$$\|\nabla_{\theta} nl(D, \theta_1) - \nabla_{\theta} nl(D, \theta_2)\| \leq C \|\theta_1 - \theta_2\|, \quad C > 0$$

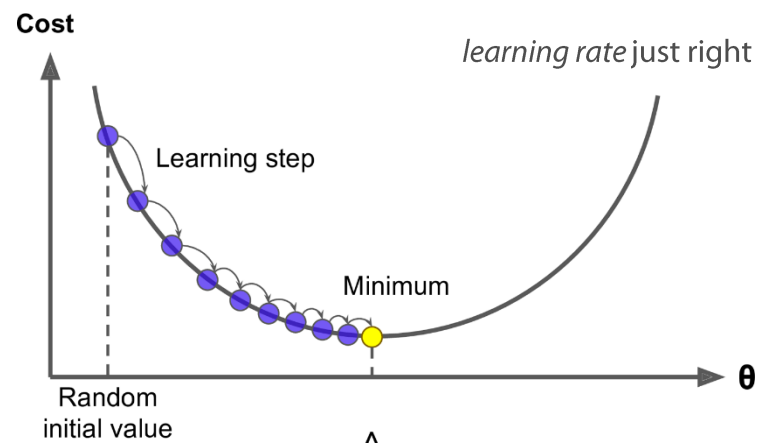
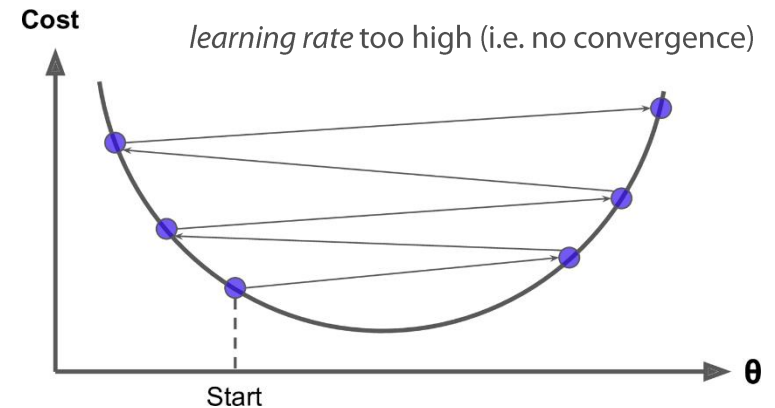
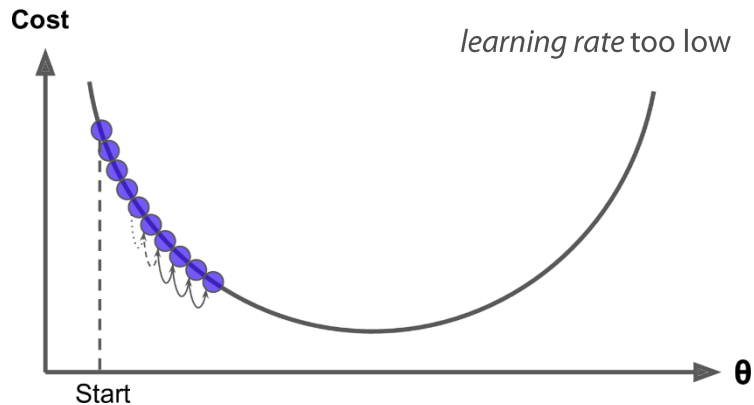
the gradient descent method converges to the optimal  $\theta^*$  for  $t \rightarrow \infty$   
provided that  $\eta \leq 1/C$

When  $nl(D, \theta)$  is *derivable, and Lipschitz continuous* but not convex  
the gradient descent method converges to a local minimum of  $nl(D, \theta)$   
under the same conditions

# Gradient Descent (GD): practicalities

## ■ Convergence in practice

The choice of the *learning rate*  $\eta$  is crucial

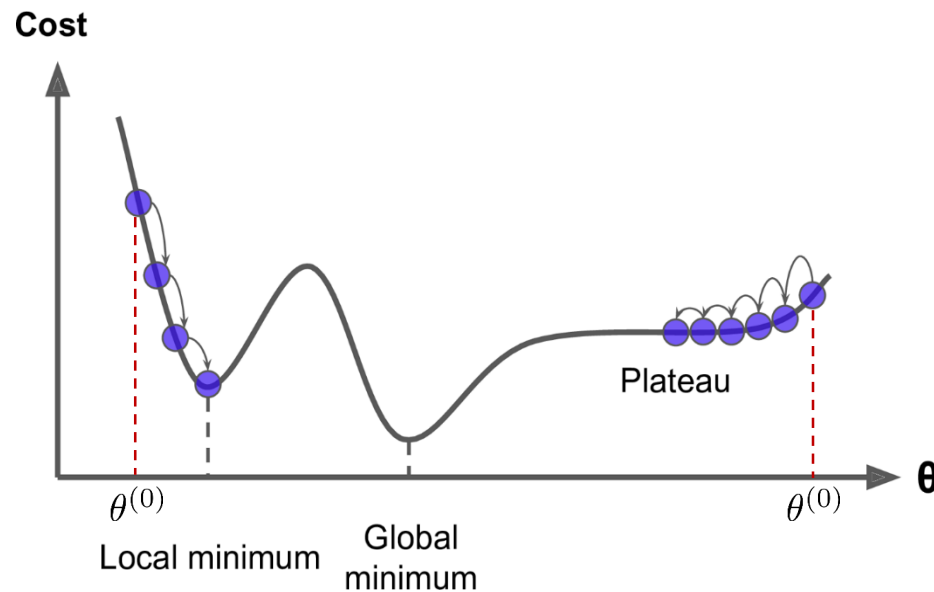


Images from <https://www.safaribooksonline.com/library/view/hands-on-machine-learning/9781491962282/ch04.html>

# Gradient Descent (GD): practicalities

- *Convergence in practice*

When  $nl(D, \theta)$  is not convex, the initial estimate  $\theta^{(0)}$  is crucial



*The outcome of the method will depend on which  $\theta^{(0)}$  is picked*

Image from <https://www.safaribooksonline.com/library/view/hands-on-machine-learning/9781491962282/ch04.html>

# Stochastic Gradient Descent (SGD): intuition

## ■ Objective

$$\theta^* := \operatorname{argmin}_{\theta} nl(D, \theta)$$

## ■ Iterative method

1. Initialize  $\theta^{(0)}$  at random
2. Pick a data item  $\langle \mathbf{x}^{(i)}, y^{(i)} \rangle \in D$  with uniform probability
3. Update  $\theta^{(t)} = \theta^{(t-1)} - \eta^{(t)} \nabla_{\theta} nl(\mathbf{x}^{(i)}, y^{(i)}, \theta^{(t-1)})$
4. Unless some termination criterion has been met, go back to step 2.

$$\eta^{(t)} \ll 1$$

Note that the *learning rate* may vary across iterations...

# Stochastic Gradient Descent (SGD): convergence

## ■ Convergence

When  $nl(D, \theta)$  is *convex, derivable, and Lipschitz continuous*, that is

$$\|\nabla_{\theta} nl(D, \theta_1) - \nabla_{\theta} nl(D, \theta_2)\| \leq C \|\theta_1 - \theta_2\|, \quad C > 0$$

the stochastic gradient descent method converges to the optimal  $\theta^*$  for  $t \rightarrow \infty$  provided that

$$\eta^{(t)} \leq \frac{1}{Ct} \quad \text{Note that } \eta^{(t)} \rightarrow 0 \text{ for } t \rightarrow \infty$$

When  $nl(D, \theta)$  is *derivable, and Lipschitz continuous* but not convex the gradient descent method converges to a local minimum of  $l(D, \theta)$  under the same conditions



# Convergence rate comparison

Assume  $nl(D, \theta)$  convex, derivable, and Lipschitz continuous

Accuracy  $\rho$  is attained when

$$|nl(D, \theta^{(t)}) - nl(D, \theta^*)| \leq \rho$$

Define also

$$N := |D|$$

Size of data space

$$d := \dim(\mathcal{V})$$

Dimension of parameter space

Time := time required to compute  $\frac{\partial}{\partial \theta_j} nl(\mathbf{x}^{(i)}, y^{(i)}, \theta)$

Algorithm	Cost per iteration	Iterations to reach accuracy $\rho$	Time to reach accuracy $\rho$
Gradient descent (GD)	$\mathcal{O}(Nd)$	$\mathcal{O}\left(\log \frac{1}{\rho}\right)$	$\mathcal{O}\left(Nd \log \frac{1}{\rho}\right)$
Stochastic gradient descent (SGD)	$\mathcal{O}(d)$	$\mathcal{O}\left(\frac{1}{\rho}\right)$	$\mathcal{O}\left(d \frac{1}{\rho}\right)$

from Bottou & Bousquet, 2007

# Convergence rate comparison

Assume  $nl(D, \theta)$  convex, derivable, and Lipschitz continuous

Accuracy  $\rho$  is attained when

$$|nl(D, \theta^{(t)}) - nl(D, \theta^*)| \leq \rho$$

Define also

$$N := |D|$$

Size of data space

$$d := \dim(\theta)$$

Dimension of parameter space

Time := time required to compute  $\frac{\partial}{\partial \theta_j} nl(\mathbf{x}^{(i)}, y^{(i)}, \theta)$

*SGD can be much faster with large datasets!*

Algorithm	Cost per iteration	Iterations to reach accuracy $\rho$	Time to reach accuracy $\rho$
Gradient descent (GD)	$\mathcal{O}(Nd)$	$\mathcal{O}\left(\log \frac{1}{\rho}\right)$	$\mathcal{O}\left(Nd \log \frac{1}{\rho}\right)$
Stochastic gradient descent (SGD)	$\mathcal{O}(d)$	$\mathcal{O}\left(\frac{1}{\rho}\right)$	$\mathcal{O}\left(d \frac{1}{\rho}\right)$

from Bottou & Bousquet, 2007

# Mini-batch Gradient Descent (MBGD): intuition

## ■ Objective

$$\theta^* := \operatorname{argmin}_{\theta} nl(D, \theta)$$

## ■ Iterative method

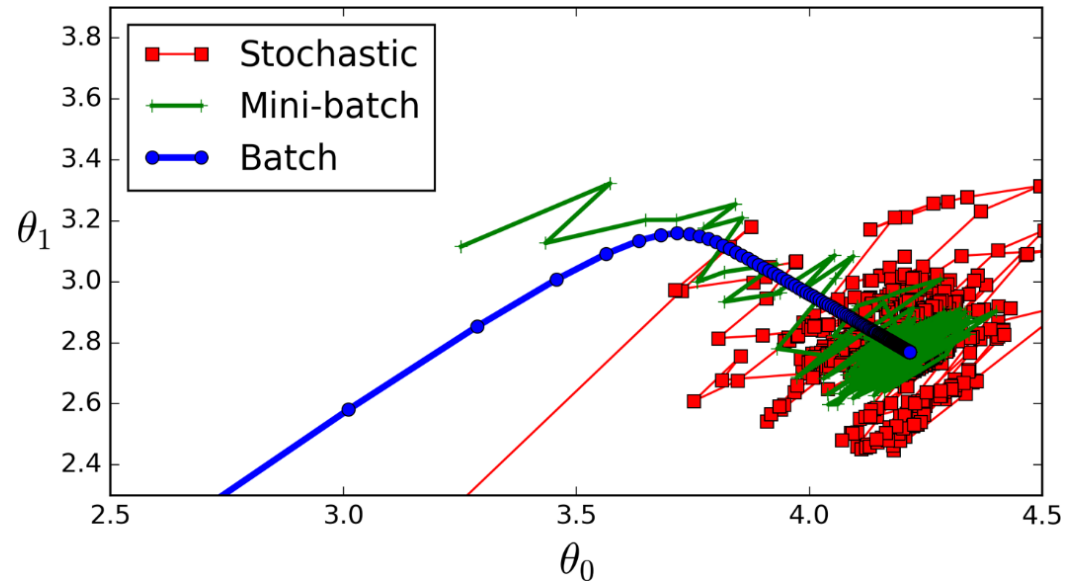
1. Initialize  $\theta^{(0)}$  at random
2. Pick a mini batch  $B \subseteq D$  with uniform probability
3. Update  $\theta^{(t)} = \theta^{(t-1)} - \eta^{(t)} \nabla_{\theta} nl(B, \theta^{(t-1)})$
4. Unless some termination criterion has been met, go back to step 2.

$$\nabla_{\theta} nl(B, \theta) := \sum_B \nabla_{\theta} nl(\mathbf{x}^{(i)}, y^{(i)}, \theta)$$

This method has the same convergence properties of SGD

# Qualitative methods comparison

Typical traces  
of the three methods  
(batch = GD)



In general:

- GD is more regular but slower (with large datasets)
- SGD is faster (with large datasets) but noisy
- MBGD is often the right compromise in practice...

Image from <https://www.safaribooksonline.com/library/view/hands-on-machine-learning/9781491962282/ch04.html>

# Back to Logistic Regression

# Logistic Regression

## ■ Maximum Likelihood Estimation

Log-likelihood

$$l(D, \theta) = \sum_{i=1}^N -\log(1 + e^{\mathbf{w}\mathbf{x}^{(i)} + b}) + \sum_{i=1}^N y^{(i)}(\mathbf{w}\mathbf{x}^{(i)} + b)$$

$$l(\mathbf{x}^{(i)}, y^{(i)}, \theta) = -\log(1 + e^{\mathbf{w}\mathbf{x}^{(i)} + b}) + y^{(i)}(\mathbf{w}\mathbf{x}^{(i)} + b)$$

This is the fundamental computation in all GD-like methods

Parameters can be expressed as:

$$\theta = (\mathbf{w}, b)$$

Hence the gradient can be split into two separate components:

$$\nabla_{\theta} l(\mathbf{x}, y, \theta) = \left( \frac{\partial}{\partial \mathbf{w}} l(\mathbf{x}, y, \theta), \frac{\partial}{\partial b} l(\mathbf{x}, y, \theta) \right)$$

*Data item indexes dropped, for simplicity*

# Logistic Regression

- Log-likelihood gradients

$$\begin{aligned}\frac{\partial}{\partial \mathbf{w}} l(\mathbf{x}, y, \theta) &= \frac{\partial}{\partial \mathbf{w}} \left( -\log(1 + e^{\mathbf{w}\mathbf{x}+b}) + y(\mathbf{w}\mathbf{x} + b) \right) \\ &= -\frac{\partial}{\partial \mathbf{w}} \log(1 + e^{\mathbf{w}\mathbf{x}+b}) + y \frac{\partial}{\partial \mathbf{w}} (\mathbf{w}\mathbf{x} + b) \\ &= -\frac{1}{1 + e^{\mathbf{w}\mathbf{x}+b}} \frac{\partial}{\partial \mathbf{w}} (1 + e^{\mathbf{w}\mathbf{x}+b}) + y\mathbf{x} \\ &= -\frac{e^{\mathbf{w}\mathbf{x}+b}}{1 + e^{\mathbf{w}\mathbf{x}+b}} \frac{\partial}{\partial \mathbf{w}} (\mathbf{w}\mathbf{x} + b) + y\mathbf{x} \\ &= -\frac{e^{\mathbf{w}\mathbf{x}+b}}{1 + e^{\mathbf{w}\mathbf{x}+b}} \mathbf{x} + y\mathbf{x} \\ &= -\sigma(\mathbf{w}\mathbf{x} + b)\mathbf{x} + y\mathbf{x}\end{aligned}$$

# Logistic Regression

- Log-likelihood gradients

$$\begin{aligned}\frac{\partial}{\partial b} l(\mathbf{x}, y, \theta) &= \frac{\partial}{\partial b} (-\log(1 + e^{\mathbf{w}\mathbf{x}+b}) + y(\mathbf{w}\mathbf{x} + b)) \\ &= -\frac{\partial}{\partial b} \log(1 + e^{\mathbf{w}\mathbf{x}+b}) + y \frac{\partial}{\partial b} (\mathbf{w}\mathbf{x} + b) \\ &= -\frac{1}{1 + e^{\mathbf{w}\mathbf{x}+b}} \frac{\partial}{\partial b} (1 + e^{\mathbf{w}\mathbf{x}+b}) + y \\ &= -\frac{e^{\mathbf{w}\mathbf{x}+b}}{1 + e^{\mathbf{w}\mathbf{x}+b}} \frac{\partial}{\partial b} (\mathbf{w}\mathbf{x} + b) + y \\ &= -\frac{e^{\mathbf{w}\mathbf{x}+b}}{1 + e^{\mathbf{w}\mathbf{x}+b}} + y \\ &= -\sigma(\mathbf{w}\mathbf{x} + b) + y\end{aligned}$$



# Logistic Regression: qualitative example

## ■ IRIS dataset

<https://archive.ics.uci.edu/ml/datasets/iris>

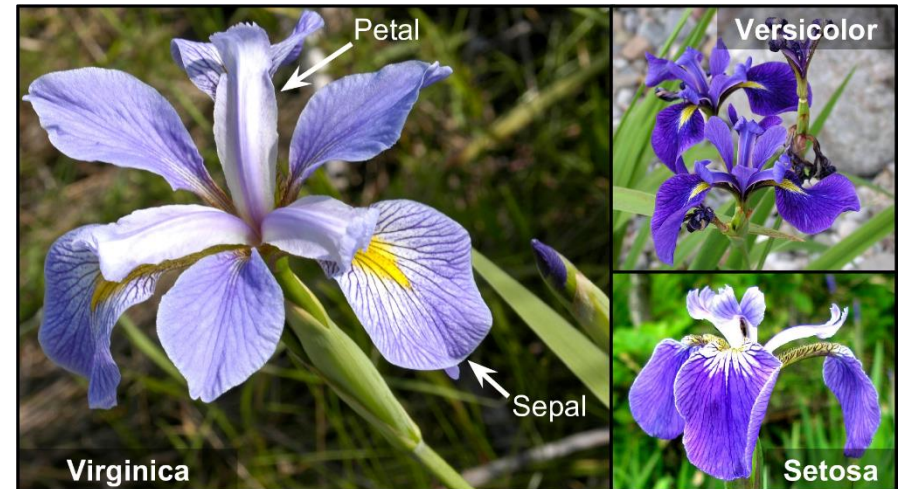
Three classes

(Iris Setosa, Iris Versicolour, Iris Virginica)

Numerical data

(petal length & width, sepal length & width)

150 data items (50 per each class)



Consider just one class: Iris Virginica  
(the other class is the complement)  
and petal width as unique input feature

Apply logistic regression (with any GD-like method)

This will be the result:

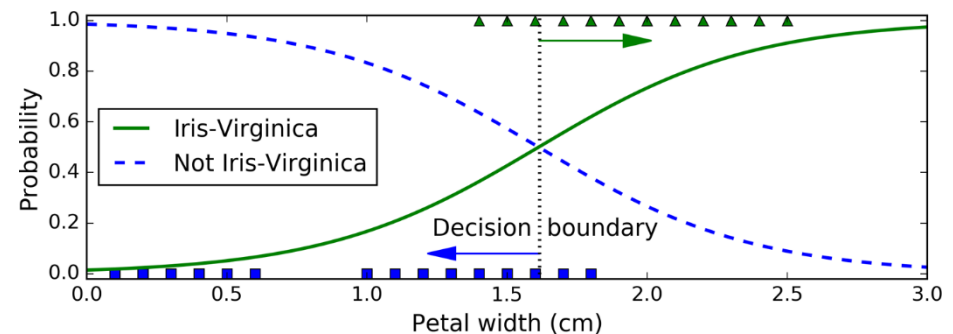


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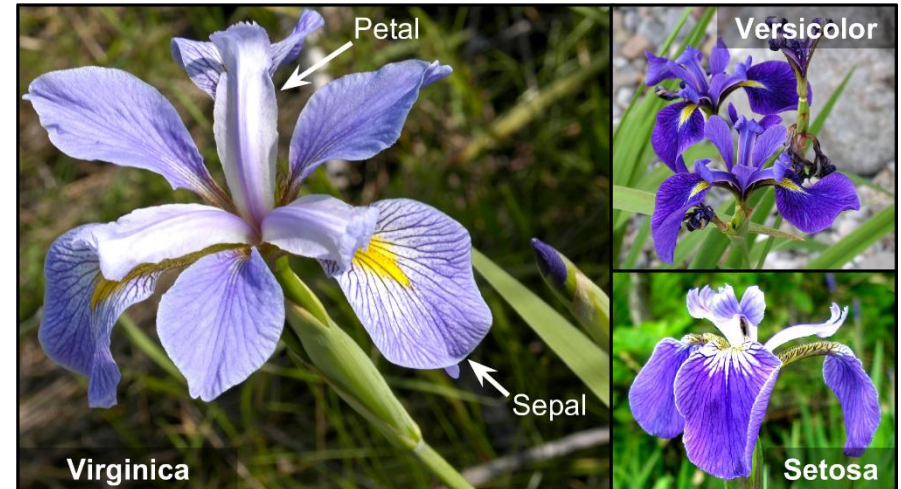
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150 data items (50 per each class)



Consider just one class: Iris Virginica

(the other class is the complement)

with petal width and petal length as input features

Apply logistic regression (with any GD-like method)

This will be the result:

The separation improves

The *linearity* of the parametrization is evident:  
the two classes must be *linearly separable*

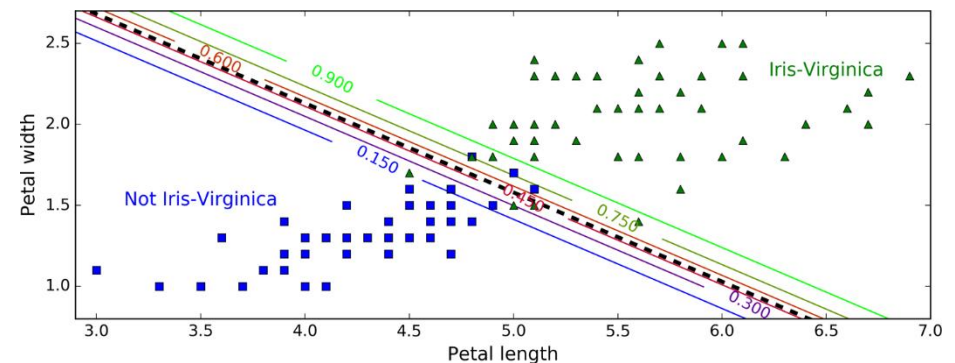


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