

Entailment and Algorithms

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Decisions and decidability (automation)

- What is a *problem*?

A *problem* is an association, i.e. a **relation** between *inputs* and *solutions*

$K : I \rightarrow S$ (K is the relation, I is the input space, S is the solution space)

- *Search problem*

Relation K associates each input to many solutions (i.e. one-to-many)

Optimization problems

A search problem plus an *objective* or *cost* function

$c : S \rightarrow \mathbf{R}$ (from S to $\mathbf{R}$, the set of real number)

In general, the task is finding the solution(s) having maximal or minimal cost

- **Decision** problem

The solution space S coincides with $\{0, 1\}$

and K associates each input to a unique solution

Example: $\Gamma \models \varphi$?

The input space I contains all possible combinations of set Γ of wffs with individual wffs φ

Decisions and decidability (automation)

■ **Decidable** problem

A decision problem K which there exists an algorithm, more precisely a *Turing machine* (there are other ways of defining an algorithm or an *effective procedure*: they are all equivalent) that **always terminates** and produces the right answer in **finite time**.

Example of an *undecidable* problem: The *Halting Problem*

Given the formal description of a particular Turing machine with a specific input, is it possible to tell if whether it will eventually halt or run forever?

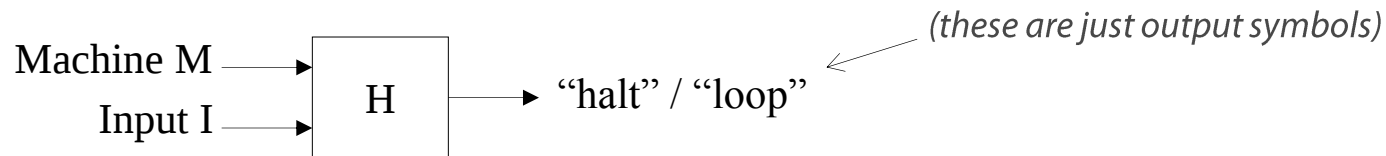
In other words, does it exist a Turing machine that, given in input the description of *another* Turing machine, will always produce the answer desired?

The answer is **no** (such a Turing machine *cannot* exist)

An aside: The *Halting Problem*

- Intuitive ideas behind the proof (i.e. of the *undecidability* of this problem)

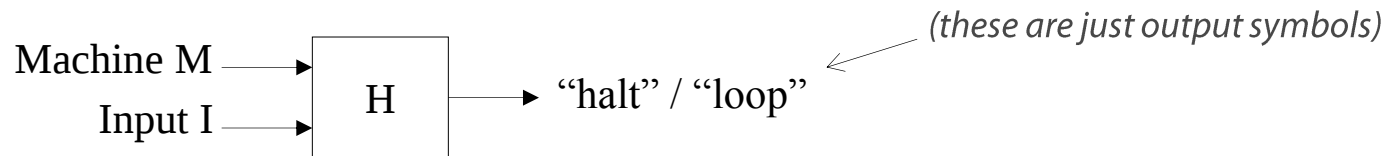
Let's assume there exists a Turing machine H that, given the description of a Turing machine M with input I always terminates producing an output “halt” or “loop” depending on whether M with input I will terminate or not



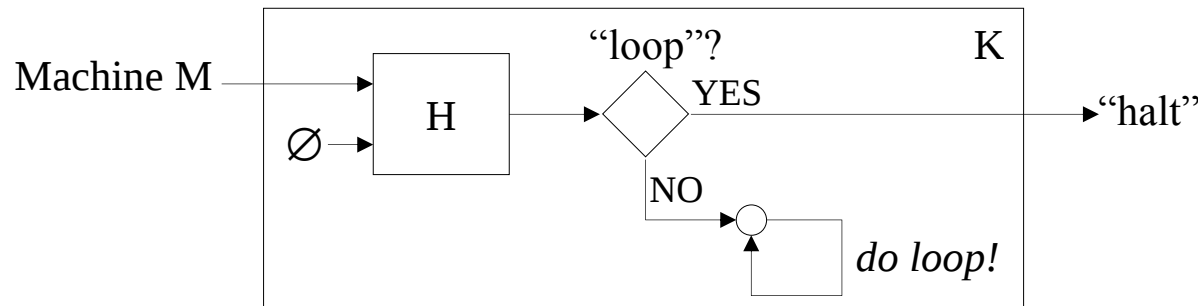
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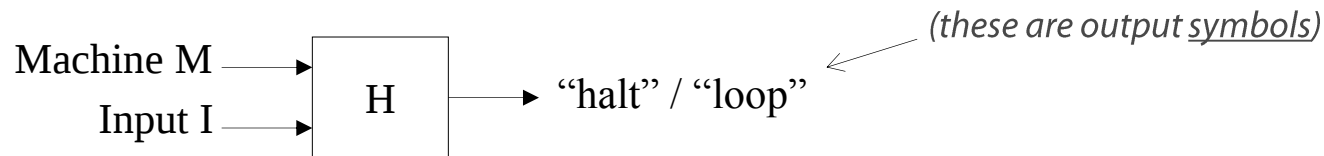
Assume H existed and consider the subclass of Turing machines having an empty input. We can build another Turing machine K that enters an infinite loop whenever the output of H is “halt” and that terminates, with output “halt”, when H outputs “loop”



An aside: The *Halting Problem*

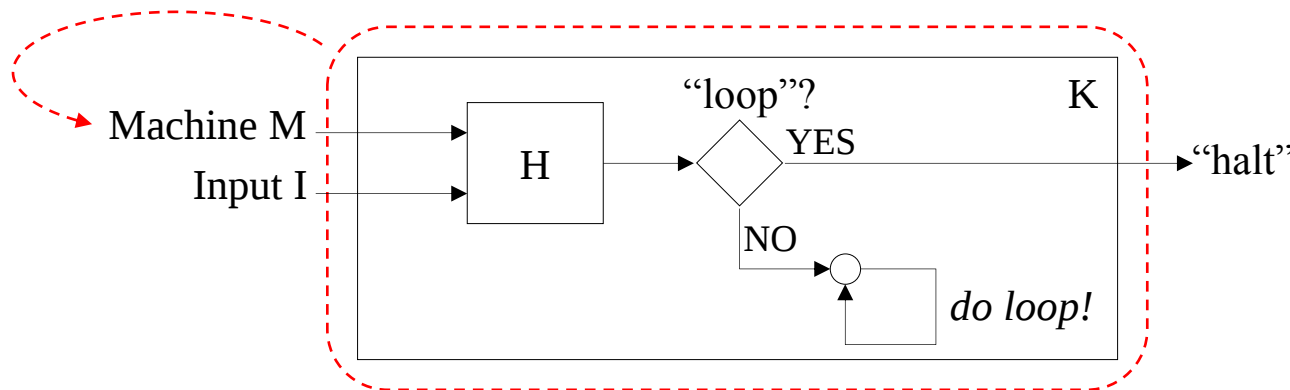
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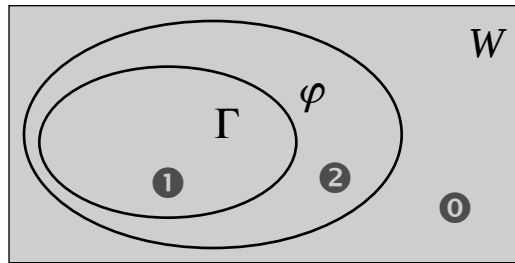
What will be the output of K when given K *itself* as the input?

K should *diverge* when K *terminates* and vice-versa: i.e. we have an absurdity

Transforming problems: entailment as satisfiability

- The decision problem “ $\Gamma \models \varphi$? ”
can be transformed into a *satisfiability* problem

In fact, $\Gamma \models \varphi$ iff $\Gamma \cup \{\neg\varphi\}$ is *not* satisfiable



($w(\Gamma)$ is the set of possible worlds that satisfy Γ)

$$\Gamma \models \varphi \Rightarrow w(\Gamma) \subseteq w(\{\varphi\})$$

$$\mathbf{1} \subseteq \{\mathbf{1}, \mathbf{2}\}$$

$$w(\{\neg\varphi\}) = \mathbf{0}$$

$$w(\Gamma \cup \{\neg\varphi\}) = w(\Gamma) \cap w(\{\neg\varphi\})$$

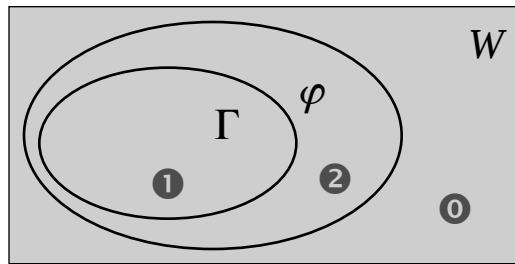
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- The decision problem “is $\Gamma \cup \{\neg\varphi\}$ satisfiable?”
can be transformed into a wff *satisfiability* problem

Taking this one step further, we can transform $\Gamma \cup \{\neg\varphi\}$ into *just one formula*:

$$\bigwedge (\Gamma \cup \{\neg\varphi\})$$

↖ This is the wff obtained by combining all the wffs in $\Gamma \cup \{\neg\varphi\}$ with $\wedge$,
it is called the *conjunctive closure* of the set $\Gamma \cup \{\neg\varphi\}$

Satisfiability and decidability (in L_P)

- Is the decision problem “is the wff φ satisfiable?” decidable?

It can be transformed into a *search* problem

i.e. finding a possible world (in the set of all possible worlds) that satisfies φ

In the scientific literature, this problem is called “SAT”

Intuition: we can try every possible value assignment for the atoms in φ

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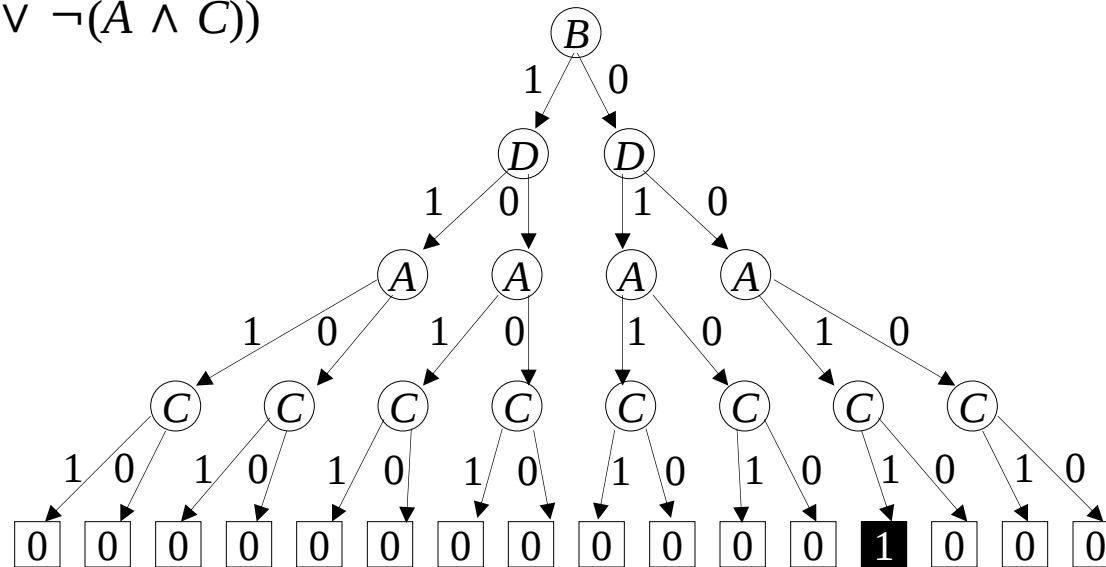
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Example:

$$\neg(B \vee D \vee \neg(A \wedge C))$$



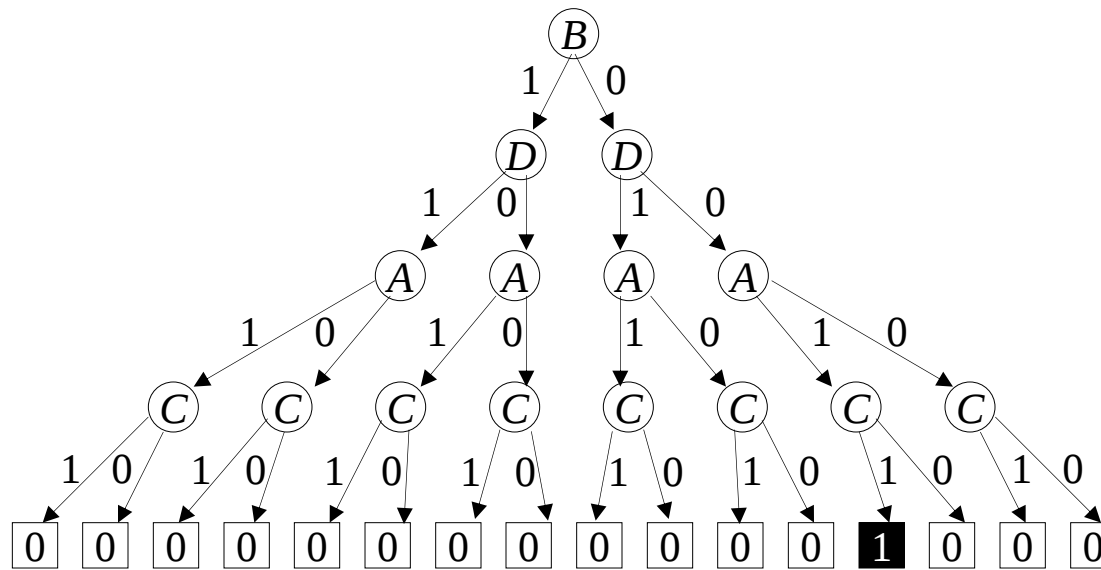
This method $O(2^n)$ time complexity, due to the number of value assignments

Satisfiability and decidability (in L_P)

Example:

$\neg(B \wedge D \wedge \neg(A \wedge C))$ which is equivalent to
 $(\neg B \vee \neg D \vee (A \wedge C))$

Each branch in the tree represents a possible assignment:



A real-world algorithm
would stop here

The same algorithm is forced to try all possible assignments
when ψ is *not* satisfiable.

For instance: $(\neg B \wedge \neg D \wedge \neg A \wedge \neg C)$

Computational complexity, classes P and NP

These notions apply to decidable problems only

It is based on the performances of a (known) Turing machine that gives the answer with respect to the *worst case* (i.e. the less favorable input for the specific problem)

- Time complexity

The number of steps that the Turing machine requires for computing the answer, as a function of some numerical dimension of the input (e.g. the number of atoms in a wff)

- Memory complexity

The number of tape cells that the Turing machine requires for computing the answer, as a function of some numerical dimension of the input

- Class P

The class of problems for which there is a Turing machine that requires $O(P(n))$ time where $P(\)$ is a polynomial of finite degree and n is the dimension of the (*worst-case*) input

- Class NP

The class of all problems:

a) A method for enumerating all possible answers (i.e. *recursive enumerability*)

b) An algorithm in class P that verifies if a possible answer is also a *solution*

It includes all problems in class P (that is, $P \subseteq NP$)

Class NP-complete and the SAT problem

- Class NP-complete

It is a subclass of NP ($\text{NP-complete} \subseteq \text{NP}$)

A problem K is NP-complete if every problem in class NP is reducible to K

- Reducibility

For class NP-complete

Consider a problem K for which a decision algorithm $M(K)$ is known

A problem J is reducible to K if there exist a decision algorithm $M(J)$ such that:

- a) algorithm $M(K)$ is called just once, as a “subroutine”, at the end of $M(J)$
- b) apart from $M(K)$, $M(J)$ has polynomial complexity

- The problem SAT

Is NP-complete (*historically, it is the first one to be known*)

Moral: if we had a polynomial decision algorithm for SAT, we would also have that

$$P = NP$$

This fact is not known, it is believed that: $P \neq NP$

(and a lot will change in the digital world, if this proves to be false)

Semantic Tableau, alpha and beta rules

- *Semantic tableau* is a method
 - which can be implemented as a Turing machine
- It is a decision algorithm for the problem
“is Σ satisfiable?”
 - where Σ is a set of wffs in L_P

In spite of its name, it is a *symbolic* method: it works on the structure of wffs only
No explicit assignments of (semantic) values are involved

Semantic Tableau, alpha and beta rules

- A tableau is a set of wffs in L_P

The method starts from an *initial* tableau

(i.e. the set Σ whose satisfiability is to be determined)

It is based on rules that transform each one wff into two wffs

- Alpha rules (i.e. expansion)

(a1)

$$\begin{array}{c} \neg(\neg\varphi) \\ | \\ \varphi \end{array}$$

(a2)

$$\begin{array}{c} \varphi \wedge \psi \\ | \\ \varphi, \psi \end{array}$$

(a3)

$$\begin{array}{c} \neg(\varphi \vee \psi) \\ | \\ \neg\varphi, \neg\psi \end{array}$$

(a4)

$$\begin{array}{c} \neg(\varphi \rightarrow \psi) \\ | \\ \varphi, \neg\psi \end{array}$$

- Beta rules (i.e. bifurcation)

(b1)

$$\begin{array}{c} \varphi \vee \psi \\ \swarrow \quad \searrow \\ \varphi \quad \psi \end{array}$$

(b2)

$$\begin{array}{c} \neg(\varphi \wedge \psi) \\ \swarrow \quad \searrow \\ \neg\varphi \quad \neg\psi \end{array}$$

(b3)

$$\begin{array}{c} \varphi \rightarrow \psi \\ \swarrow \quad \searrow \\ \neg\varphi \quad \psi \end{array}$$

(b4)

$$\begin{array}{c} \varphi \leftrightarrow \psi \\ \swarrow \quad \searrow \\ \neg\varphi, \neg\psi \quad \varphi, \psi \end{array}$$

(b5)

$$\begin{array}{c} \neg(\varphi \leftrightarrow \psi) \\ \swarrow \quad \searrow \\ \neg\varphi, \psi \quad \varphi, \neg\psi \end{array}$$

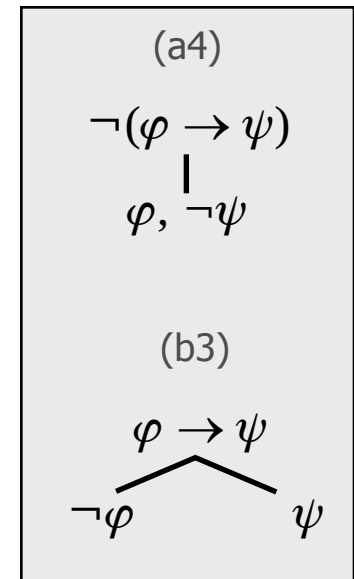
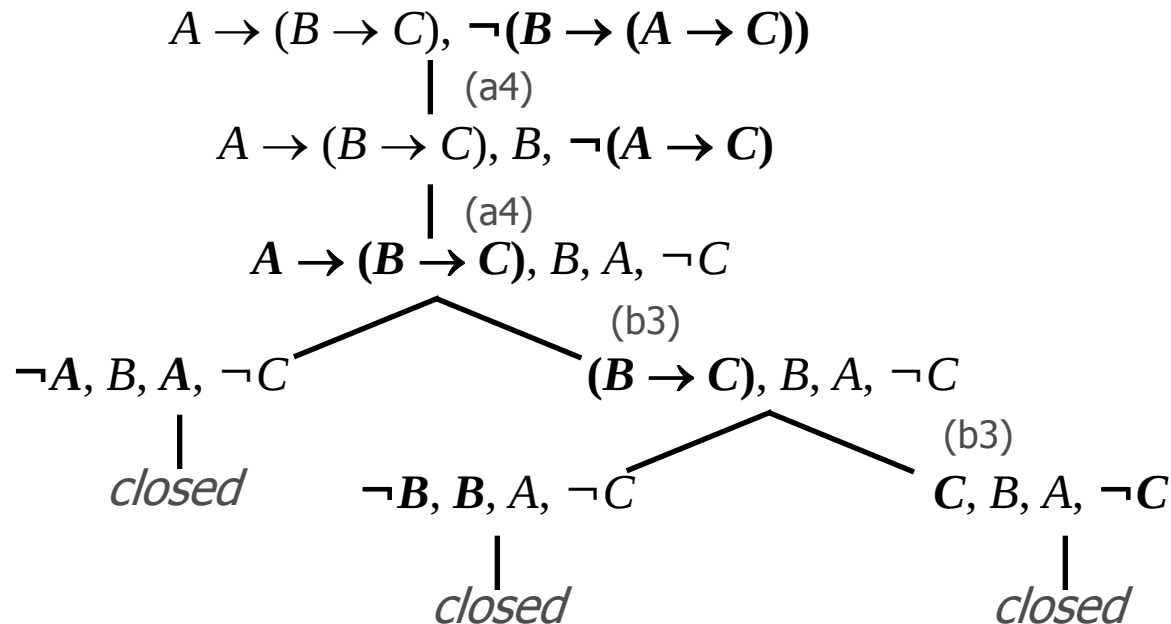
Semantic Tableau – a working example

- Original problem: “ $\Gamma \models \varphi$?”

Example input: $A \rightarrow (B \rightarrow C) \models B \rightarrow (A \rightarrow C)$?

- Transformed problem: “is $\Gamma \cup \{\neg\varphi\}$ satisfiable?”

Hence the initial tableau is $\Gamma \cup \{\neg\varphi\}$



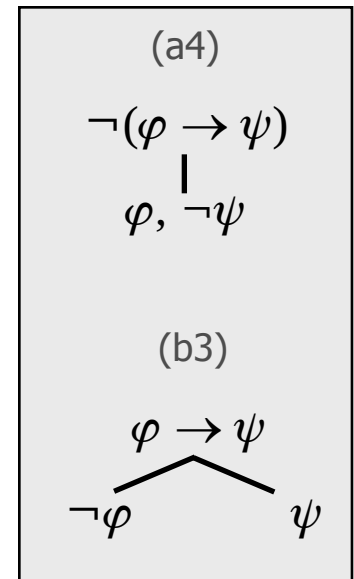
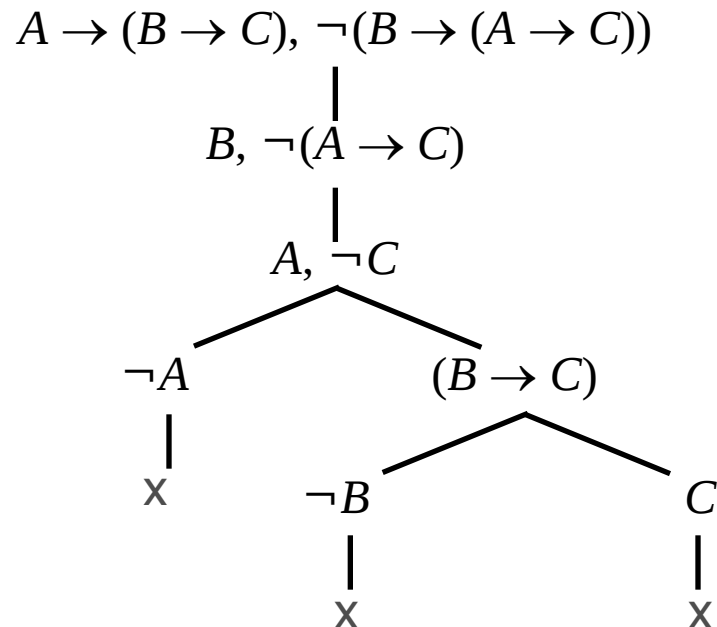
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The usual notation in textbooks is even more concise:

only those wffs that are *added* to the initial tableau in each branch are shown in the tree

Semantic Tableau – algorithm recap

- **Algorithm** (informal description – see Lab for the implementation):

Input problem: “ $\Gamma \models \varphi$? ”

The input problem is transformed into “is $\Gamma \cup \{ \neg \varphi \}$ satisfiable?”

Methods of this type are also called ‘*by refutation*’

For each active tableau (i.e. the *leaves* in the tree),

There could be two cases:

- 1) The tableau contains only *literals*

If the tableau contains a *complementary pair of literals*

then declare it *closed*

else declare it *open* (i.e. failure)

- 2) The tableau contains one or more *composite* wff

First try to apply an *alpha* rule,

otherwise, if this is not possible, try to apply a *beta* rule.

In either case, two new tableau will be generated

Output: the tree structure of tableau

Semantic Tableau – (required) algorithm properties

■ **Termination**

The algorithm never *diverges* (i.e. it never enters an infinite loop)

Each application of either alpha or beta rule *simplifies* a wff (i.e. it makes it *less* composite):
so the application of rules cannot continue forever

■ ***Symbolic derivation***

As already stated, in spite of its name, this is a *symbolic* method

We write

$$\Gamma \vdash_{ST} \varphi$$

iff the *Semantic Tableau* method is successful (i.e. all leaves are *closed*) for $\Gamma \cup \{\neg\varphi\}$

How do we know that $\Gamma \vdash_{ST} \varphi \Rightarrow \Gamma \models \varphi$?

(*Soundness* - also *correctness* - of the method)

Exercise: prove it

(*hint*: consider the condition on $\Gamma \cup \{\neg\varphi\}$ and think about how it relates to each *rule*)

How do we know that $\Gamma \models \varphi \Rightarrow \Gamma \vdash_{ST} \varphi$?

(*Completeness* of the method)

Proving it is definitely more difficult: see textbook (i.e. Ben-Ari)

Semantic Tableau – (required) algorithm properties

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- **Soundness**

$$\Gamma \vdash_{ST} \varphi \Rightarrow \Gamma \models \varphi$$

- **Completeness**

$$\Gamma \models \varphi \Rightarrow \Gamma \vdash_{ST} \varphi$$

- **Termination + Soundness + Completeness = *Decision Algorithm***

(for propositional logic)

Which method is faster?

- Time complexity (remember: consider the *worst case*)

The 'brute-force search' and *Semantic Tableau* have the same complexity : $O(2^n)$

- *How well do these method perform in practice?*

It depends

Example 1 (try it):

$$A \wedge B \wedge C \wedge \neg A$$

The 'brute-force search' requires $2^3 = 8$ attempts

The Semantic Tableau method requires applying the same alpha rule 3 times

Example 2 (try it):

$$(A \vee B) \wedge (A \vee \neg B) \wedge (\neg A \vee B) \wedge (\neg A \vee \neg B)$$

The 'brute-force search' requires $2^2 = 4$ attempts

The Semantic Tableau method requires applying the same alpha rule 3 times; then the same beta rule is applied exhaustively producing a tree with 4 levels, with each node in a tree with a branching factor 2

At the end, the tree has $2^4 = 16$ leaves (all *closed* tableau)